Parity, Skein Polynomials and Categorification

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October 25, 2011

Abstract

We investigate an application of crossing parity for the bracket expansion of the Jones polynomial for virtual knots. In addition we consider an application of parity for the arrow polynomial as well as for the categorifications of both polynomials. We present a number of examples found through our calculations. We provide tables of calculations for these invariants on virtual knots with at most 4 real crossings.

Key Words: Jones Polynomial, Arrow Polynomial, Parity, Categorification, Khovanov Homology, Virtual Knot, Flat Virtual Knot, Graphical Jones Polynomial, Graphical Arrow Polynomial, Graphical Khovanov Homology

1 Introduction

Since the introduction of virtual knot theory, crossing parity has provided a valuable resource for creating invariants. (See Definition 3.1 in the present paper for our definition of crossing parity.) For instance, given a virtual knot the odd writhe [23] (i.e. sum of the signs of the odd crossings) is an easily computable invariant. Recently, Manturov introduced a parity version of the bracket polynomial [31] and described how this construction can pass to Khovanov homology via a filtration on the space of virtual knots. Our goal here is to investigate these constructions and show how we can apply a similar construction to the arrow polynomial. Along the way we show how known facts about minimal surface genus for virtual knots extend to the categorical setting.

The bracket polynomial (and Jones polynomial) as well as the arrow polynomial have a rich history. For an introduction to virtual knot theory we recommend [19]. For an introduction to the bracket polynomial we point the reader

to [21] and [22]. Similarly, for the arrow polynomial we recommend the paper [18] as well as the work of Dye and Kauffman in [8] [9]. Note that the arrow polynomial is equivalent to the Miyazawa polynomial as constructed in [35] and [36]. We use the term arrow polynomial as our definition follows the construction introduced by Dye and Kauffman.

The Jones polynomial was categorified by Khovanov in [26] and for an introduction to Khovanov homology we point the reader to Bar-Natan [4], [5] and Kauffman [20]. Since Khovanov's seminal work categorification in classical knot theory has been a fruitful topic of research. Notably, Rasmussen [37] used a spectral sequence introduced by Lee [29] to produce a lower bound on the slice genus for a classical knot. Recently it was also announced by Kronheimer and Mrowka [28] that Khovanov homology detects the unknot by showing there is a spectral sequence from (reduced) Khovanov homology to instanton Floer homology. This is exciting news as it provides support for the similar conjecture for the Jones polynomial.

The study of Khovanov homology in relation to virtual knot theory is still rather new. The introduction of the virtual crossing brings with it a new diagram for the unknot which has the property $d^2=0$ (using Khovanov's original definition) only for coefficients in \mathbb{Z}_2 (see Figure 6 of [30]). A wonderful explanation of how far we can take Khovanov's original work is given by Viro in [39]. To work around this new problem methods have been introduced by Asaeda, Przytycki, and Sikora [1] as well as Manturov [32]. The Asaeda-Przytycki-Sikora approach requires not only a diagram but an embedding in a (fixed) thickened surface. On the other hand, Manturov's version introduces a signed, oriented and ordered basis on the states of the cube complex to make all faces commute.

Other than its introduction in [10] and recent review in [19], little has been written about the categorifications of the arrow polynomial. In this regard we produce lower bounds for the homological width of the fully-graded categorification and we as extend bounds for the surface genus to the categorical setting. In the Appendix we provide a collection of programs for computing all of the invariants discussed in this paper. We hope these programs will increase the awareness and interest in the study of these categorifications.

1.1 Virtual Knots

In [24] Kauffman introduced virtual knots and links as a natural extension of classical knots and links. Virtual knot theory can be thought of both as (1) equivalence classes of embeddings of closed curves in a thickened surface (possibly non-orientable) up to isotopy and handle stabilization on the surface and (2) the completion of the signed oriented Gauss codes (i.e. an arbitrary Gauss code corresponds to a virtual knot while not every Gauss code corresponds to a classical knot.)

We recall in Figure 1 the Reidemeister Moves for classical knot diagrams. Figure 2 displays the additional Virtual Reidemeister Moves for the theory in terms of planar diagrams. Here we have introduced the *virtual crossing* which is neither an under-crossing or over-crossing. We represent the virtual crossing by two arcs which cross and have a circle around the crossing point.

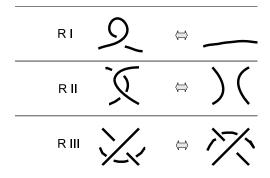


Figure 1: Reidemeister Moves

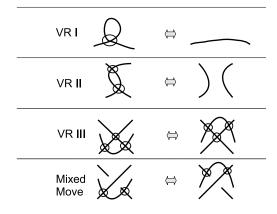


Figure 2: Virtual Reidemeister Moves

Note that the move in Figure 3 is not an equivalence relation for diagrams of virtual knots and links. It can be shown that adding this relation and its mirror image to the Virtual Reidemeister Moves allows one to unknot any virtual knot. For this reason we refer to this move as the *forbidden move*. Adding just one of these two forbidden moves yields a nontrivial theory called welded knots [12].

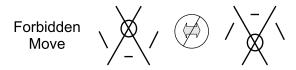


Figure 3: The "Forbidden Move"

1.2 The Normalized Bracket Polynomial

For completeness we recall the construction of the bracket polynomial introduced by Kauffman in [21].

Definition 1.1. Given a diagram D for a virtual knot K the bracket polynomial of K is defined by the relations in Figures 4.

Figure 4: Bracket Polynomial Skein Relations

To be more precise, suppose D is an n-crossing diagram for the (virtual) knot K. We generate the polynomial by smoothing every crossing in each of the two ways possible. The result of each smoothing at a particular crossing is multiplication by the term, A or A^{-1} , following the conventions of Figure 4, and we take the sum of these two weighted smoothings. For a particular crossing we call these smoothings the A-smoothing and B-smoothing respectively.

Next let $s = (s_1, \ldots, s_n)$ where $s_i \in \{0, 1\}$. Define the *state* of D corresponding to s to be the result of applying an B-smoothing at crossing i when $s_i = 0$ and an A-smoothing at crossing i when $s_i = 1$. Furthermore define $\langle D \mid s \rangle$ to be the product of A's and A^{-1} 's that label the state s multiplied by the loop value $d^{\parallel s \parallel}$ where $d = (-A^2 - A^{-2})$ and $\parallel s \parallel$ denotes the number of loops in the state. Here each state is obtained by a choice of smoothing for each crossing and is labeled with the type of smoothing at each of the smoothing sites.

Remark 1.1. This definition of the bracket polynomial is shifted from the standard definition. Here the value of a single loop is $d = (-A^2 - A^{-2})$ as opposed to 1 in the standard definition. This has the effect that our definition is $d \times \langle \langle K \rangle \rangle$, where $\langle \langle K \rangle \rangle$ is the standard definition of the bracket polynomial as in [21].

Definition 1.2. Let S be the collection of all states of a diagram D for a knot K. We may define the bracket polynomial of K to be

$$\langle K \rangle = \sum_{s \in \mathcal{S}} \langle D \mid s \rangle$$

It follows from this definition that the state sum is well defined and the expansion identities in Figure 4 follow from the state sum definition.

Definition 1.3. Given a virtual knot K with diagram D, the normalized bracket polynomial of K is given by

$$f_A(K) = f_A(D) = (-A)^{-3\omega(D)} \langle D \rangle$$

where $\langle D \rangle$ is the bracket polynomial of D and

 $\omega(D) = writhe(D) = (\# positive crossings in D) - (\# negative crossings in D).$

Theorem 1.1. The normalized bracket polynomial is an invariant of (virtual) knots.

Proof. Here each loop, regardless of virtual crossings, evaluates as the loop value d. See [21] \blacksquare

1.3 The Arrow Polynomial

Similarly we recall the construction of the arrow polynomial. Given a diagram D for a virtual knot K the (un-normalized) arrow polynomial of K is defined by the smoothing relations in Figure 5 analogous to the prior construction of the bracket polynomial and reduction relations in Figure 6.

$$\left\langle \begin{array}{c} \begin{array}{c} \\ \end{array} \right\rangle_{A} = A \left\langle \begin{array}{c} \\ \end{array} \right\rangle \left\langle \begin{array}{c} \\ \end{array} \right\rangle_{A} + A^{-1} \left\langle \begin{array}{c} \\ \end{array} \right\rangle_{A}$$

$$\left\langle \begin{array}{c} \\ \end{array} \right\rangle_{A} = A \left\langle \begin{array}{c} \\ \end{array} \right\rangle_{A} + A^{-1} \left\langle \begin{array}{c} \\ \end{array} \right\rangle_{A}$$

Figure 5: Arrow Polynomial Crossing Relations

Notice that the smoothing relations for the arrow polynomial depend on the sign of the crossing. While we still have an A-smoothing and B-smoothing and will refer to these choices, we also differentiate the smoothings by whether they agree with the original (pre-smoothed) orientation of the knot diagram. If the orientations agree we call these oriented smoothings else they are disoriented smoothings. The disoriented smoothings create cusps in the state which satisfy the relations in Figure 6. Moreover, these cusps introduce an infinite family of variables $\{K_n\}, n \in \mathbb{N}$. That is, we cancel consecutive cusps pointing in the same direction (locally both inward or outward) and resolve virtual crossings following the rules in Figure 6. The remaining 2n alternately-oriented cusps on a loop are counted and we assign the loop the value $\{K_n\}$ when n > 0. We refer to these variables as arrow numbers [9] [18].

$$\left\langle \begin{array}{c} \begin{array}{c} \\ \\ \end{array} \right\rangle_{A} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{A}$$

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Figure 6: Arrow Polynomial Reduction Relations

Definition 1.4. Given a virtual knot K with diagram D, the un-normalized arrow polynomial of K is given by

$$\langle D \rangle_A = \sum_{s \in \mathcal{S}} \langle D \mid s \rangle_A$$

where S is the collection of all states of D.

Definition 1.5. Given a virtual knot K with diagram D, the normalized arrow polynomial of K is given by

$$AP(K) = AP(D) = (-A)^{-3\omega(D)} \langle D \rangle_A$$

where $\langle D \rangle_A$ is the arrow polynomial of D and

 $\omega(D) = writhe(D) = (\# positive crossings in D) - (\# negative crossings in D).$

Theorem 1.2. The normalized arrow polynomial is an invariant of virtual knots.

Proof. See [18]. ■

Remark 1.2. The Jordan Curve Theorem implies that the arrow polynomial is equivalent to the normalized bracket polynomial for classical knots.

1.3.1 The Arrow Polynomial and Surface Genus

Recall that virtual knots are in 1-1 correspondence with equivalence classes of knots in thickened oriented surfaces modulo 1-handle stabilization and Dehn twists. This raises the question, given a knot, what is the minimal genus for this embedding.

Definition 1.6. Given a virtual knot K, the (orientable) surface genus of K, s(K), is the minimal genus of the surface S_g such that $S^1 \hookrightarrow S_g \times I$ corresponds to K.

Theorem 1.3. (Theorem 4.5 of [9]) Let K be a virtual knot diagram with arrow polynomial $\langle K \rangle_A$. Suppose that $\langle K \rangle_A$ contains a summand with the monomial $K_{i_1}^{e_1}K_{i_2}^{e_2}\cdots K_{i_n}^{e_n}$ where $i_j \neq i_k$ for all j, k in the set $\{1,2,\ldots,n\}$. Then n determines a lower bound on the genus g of the minimal genus surface in which K embeds. That is, if $n \geq 1$ then the minimum genus is 1 or greater and for $g \geq 2$ if n > 3g - 3 then s(K) > g.

Proof. The proof follows from showing that non-zero arrow numbers correspond to essential curves on the surface. The bounds follow from considering the maximal number of non-intersecting essential curves on the surface which do not bound annuli.

Remark 1.3. In the g=1 case it can be shown that if there is more than 1 non-intersecting essential curve then they must bound an annulus. Hence if $\langle L \rangle_A$ contains a summand with a monomial of the form K_iK_j with $i \neq j$ then the minimal surface genus is at least 2.

1.4 Examples

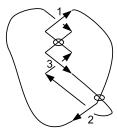


Figure 7: Virtual Knot 3.1

Following the naming conventions in Jeremy Green's virtual knot tables [13] we consider virtual knot 3.1 as shown in Figure 7. Figures 8 and 9 show how one uses the state-sum formulas from the previous sections to arrive at the respective polynomials. Note that by the previous theorem the arrow polynomial gives that the surface genus of virtual knot 3.1 is at least one. The diagram above has surface genus 2.

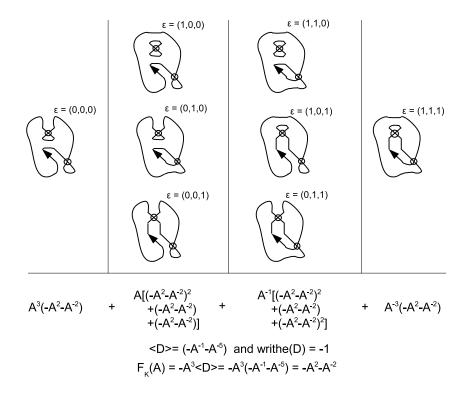


Figure 8: Virtual Knot 3.1 Bracket Polynomial State-Sum

2 Categorification

2.1 Khovanov Homology for Virtual Knots

For completeness we recall the definition of Khovanov homology [26] [27]. Our construction follows closely that of Dror Bar-Natan [4] and Kauffman [19]. For other descriptions of the construction we point the reader to Khovanov [26] [27], Wehrli [40], Viro [39], Shumakovitch [38], Elliott [11], Kauffman[19], and Manturov [32]. For technical reasons involving the construction of the categorification of the arrow polynomial we will take coefficients over the field \mathbb{Z}_2 . It should be noted that the construction of Khovanov homology for virtual knots can be extended to arbitrary coefficients following the construction of Manturov in [32]. As one would expect, Manturov's definition is equivalent to that of Khovanov for classical knots.

Before we recall the construction, we first rewrite the normalized bracket polynomial in order to simplify the definition. For a given virtual knot or link K with corresponding diagram D, let c(K) denote the crossing number of D. Sending $\langle K \rangle$ to $A^{-c(K)}\langle K \rangle$ and A to $-q^{-1}$ we get the following definition of the

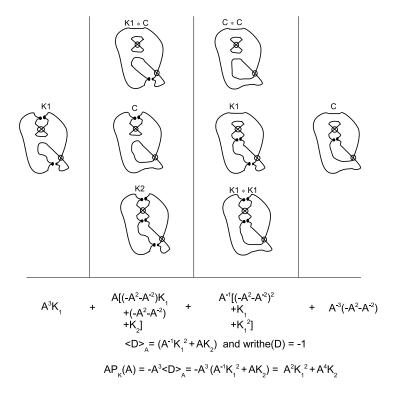


Figure 9: Virtual Knot 3.1 Arrow Polynomial State-Sum

bracket polynomial:

$$\langle \emptyset \rangle = 1 \; ; \; \langle \bigcirc K \rangle = (q + q^{-1}) \langle K \rangle \; ; \; \langle \searrow \rangle = \langle \searrow \rangle - q \langle \rangle \langle \rangle$$

And, as pointed out in Bar-Natan [4] we can summarize the Khovanov bracket via the axioms:

$$\llbracket \varnothing \rrbracket = 0 \to \mathbb{Z}_2 \to 0 \; ; \; \llbracket \bigcirc K \rrbracket = V \otimes \llbracket K \rrbracket \; ; \; \llbracket \diagdown \rrbracket = \operatorname{Cone}(\llbracket \widecheck{\diagup} \rrbracket \overset{\operatorname{d}}{\to} \; \llbracket \, \big\backslash \big\langle \rrbracket \{1\})$$

where $V = \mathbb{Z}_2[X]/(X^2)$, $\{1\}$ is the "degree shift by one" operation on the quantum grading and *Cone* is the mapping cone over the differential d which we have yet to define. Note that we will use the enhanced state definition common in the literature, where each enhanced state corresponds to a labeling of the circle by 1 or X. This has the correspondence

$$1 \Leftrightarrow q^{+1} \text{ and } X \Leftrightarrow q^{-1}.$$

Remark 2.1. For convenience we will continue to use the terms A-smoothing and B-smoothing as defined earlier.

More constructively, consider the collection of enhanced states S arising from applying an A-smoothing and B-smoothing at each crossing and furthermore labeling each of the resulting circles by either 1 or X. Define the Khovanov complex $C^{\bullet,\bullet}$ by setting $C^{i,j}$ to be the linear span of states $s \in S$ where $i = n_B(s) =$ "the number of B-smoothings in s" and $j = j(s) = n_B(s) + \lambda(s)$ where $\lambda(s) =$ "the number of loops in s labeled 1 minus the number of loops labeled X". We will refer to i as the homological grading and j as the quantum grading.

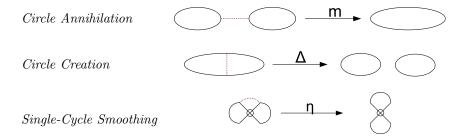
For any two states s, s' that differ by replacing an A-smoothing by a B-smoothing at a single site respectively we define a *local differential*, $d_{s,s'}$, such that the homological grading is increased by 1 and the quantum grading is preserved. Once this is defined, we then have the differential

$$d: \mathcal{C}^{i,j} \to \mathcal{C}^{i+1,j}$$

defined by

$$d(s) = \sum_{s'} d_{s,s'}$$

All that remains is to determine the possible values for $d_{s,s'}$. Since we are only concerned with resmoothing at a single site there are 3 possible scenarios relating s and s' in the setting of virtual knots.



For any circles in state s not involved in resmoothing we set $d_{s,s'}$ to act as the identity on the enhanced states. For the enhanced circles involved in the resmoothing we define m, Δ and η as follows:

$$m: \begin{cases} 1\otimes 1 & \to & 1\\ 1\otimes X & \to & X\\ X\otimes 1 & \to & X\\ X\otimes X & \to & 0 \end{cases}$$
$$\Delta: \begin{cases} 1 & \to & 1\otimes X + X\otimes 1\\ X & \to & X\otimes X \end{cases}$$
$$\eta: \begin{cases} 1 & \to & 0\\ X & \to & 0 \end{cases}$$

We are now in a position to define the $\mathit{Khovanov}$ homology of a knot or link K,

$$\mathcal{H}(K) = [\![K]\!][-n_-]\{n_+ - 2n_-\}$$

where [l] is the shift operator on the homological grading and $\{l\}$ is the shift operator on the quantum grading. Moreover we can define the *Khovanov invariant* to be the Poincaré polynomial:

$$Kh(K):=\sum_{i,j}t^iq^jdim\mathcal{H}^{i,j}(K)$$

Example 2.1. Consider the virtual knot 3.1 in Figure 7. The Khovanov complex for the unenhanced states is shown in Figure 10. It is a small exercise to show $Kh(VK_{3.1}) = q + q^{-1}$

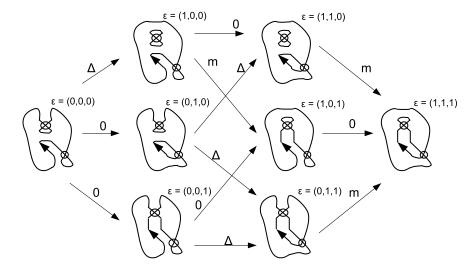


Figure 10: Virtual Knot 3.1 Khovanov Homology Complex

We will omit the well known proof that $d^2 = 0$, which amounts to checking all cases in the virtual setting, as well as the proof of invariance under the Reidemeister Moves. These details can be found in [26], [4], [5], [32], and [39].

If not for the self-imposed \mathbb{Z}_2 setting, we could also discuss applications of Lee's spectral sequence [29], [37] in the virtual setting. We plan to return to this subject in a future paper.

2.2 Categorifications of the Arrow Polynomial

In 2009 Dye, Kauffman and Manturov [10] introduced two categorifications of the arrow polynomial for virtual knots. Both constructions are homology theories defined over \mathbb{Z}_2 and agree with Khovanov homology over \mathbb{Z}_2 for classical knots. We remark that this construction is similar in flavor to the construction of Khovanov homology described in the previous section. The major difference in the constructions presented here are the considerations of additional gradings arising from the arrow numbers. We will use the same renormalization for categorification of the arrow polynomial as we did in Khovanov homology, namely sending $\langle K \rangle$ to $A^{-c(K)} \langle K \rangle$ and A to $-q^{-1}$, where c(K) is the crossing number for the diagram of K.

We first recall the construction introduced in [10] introducing the multiple grading and vector grading. Consider the collection of enhanced states S arising from applying an A-smoothing and B-smoothing at each crossing, where A- and B-smoothings are defined as in Figure 5, and furthermore labeling each of the resulting circles by either 1 or X. Define the arrow complex $\mathcal{C}_A^{\bullet,\bullet,\bullet,\bullet}$ by setting $\mathcal{C}_A^{i,j,m,v}$ to be the linear span of enhanced states $s \in S$ where $i = n_B(s) =$ "the number of B-smoothings in s" and $j = j(s) = n_B(s) + \lambda(s)$ where $\lambda(s) =$ "the number of loops in s labeled 1 minus the number of loops labeled X". We will refer to i as the homological grading and j as the quantum grading.

Given a state s define the multiple grading of s, mg(s), to be the set of arrow numbers of s.

Given an enhanced state s, consider the collection Λ_s of enhanced circles carrying nonzero arrow numbers. For a circle $c \in \Lambda$ with arrow number p let the order of c, o(c), be the value of k such that $p = 2^{k-1} * l$ with gcd(2, l) = 1. Define the function vg(c) by $vg(c) = e_{o(c)}$ if c is labeled by X and $vg(c) = -e_{o(c)}$ if c is labeled by 1, where e_1, e_2, \ldots is the standard basis for \mathbb{R}^{∞} . Then the vector grading, vg(s), is given by

$$vg(s) = \sum_{c \in \Lambda} vg(c)$$
 Example 2.2. The state $s = \bigvee^1 \bigvee_{c \in \Lambda} \bigvee^{\mathsf{X}} \bigvee^{\mathsf{X}} \bigvee^{\mathsf{X}} has$
$$mg(s) = \{K_1, K_2\} \ and \ vg(s) = (-2, 1, 0, 0, 0, \ldots)$$

As before, for any two states s, s' that differ by an A- to B- resmoothing at a single site it remains to define a local differential $d_{s,s'}$ such that the homological

grading is increased by 1 and the quantum grading, multiple grading and vector grading are all preserved. Once this is defined, we have the differential

$$d:\mathcal{C}_{A}^{i,j,m,v}\to\mathcal{C}_{A}^{i+1,j,m,v}$$

defined by

$$d(s) = \sum_{s'} d_{s,s'}$$

Finally, The local differential $d_{s,s'}$ is defined by $d_{s,s'} = \tilde{\partial}_{s,s'} \circ \partial_{s,s'}$ where $\partial_{s,s'}$ is the Khovanov local differential between the corresponding states and $\tilde{\partial}_{s,s'}$ is the projection map preserving the multiple grading and vector grading. It is a short exercise to show that this satisfies the requisite $d^2 = 0$ through checking all possible cases. A key observation for the proof is noting that for circle annihilation and circle creation arrow numbers are \pm -additive while a single cycle resmoothing causes the arrow number to change by 1 as is shown in Figure 11.

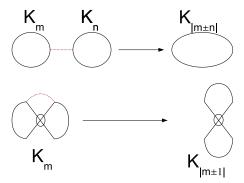


Figure 11: The Effect of Resmoothing on Arrow Numbers

We are now in a position to define the homology for the fully-graded categorification of the arrow polynomial of a knot or link K, $\mathcal{H}_A(K)$, by renormalizing analogously to Khovanov homology. Moreover we can define the *fully-graded* arrow categorification invariant to be the Poincaré polynomial:

$$AKh(K) := \sum_{i,j \in \mathbb{Z}, m \in M(D), v \in V(D)} m \times v \times t^i \times q^j \times dim \mathcal{H}_A{}^{i,j,m,v}(K)$$

where

$$S(D) = \{ \text{enhanced states of D} \}$$
 , $M(D) = \bigcup_{s \in S} mg(s)$ and $V(D) = \bigcup_{s \in S} vg(s)$

for a diagram D of K.

Example 2.3. Consider the virtual knot 3.1 in Figure 7. The cube complex for the unenhanced states is shown in Figure 12. It is a small exercise to show

$$AKh(VK_{3.1}) = \frac{vg(2,1)K[2]}{q^3t} + \frac{vg(1,2)K[1]}{q^3} + \frac{vg(2,-1)K[2]}{qt} + qvg(1,-2)K[1] + \frac{2K[1]}{q} +$$

Remark 2.2. To translate the polynomial into the form of the definition one only has to see how to read the multiple grading and vector grading for a given monomial. The multiple grading is simply the collection of coefficients of the form $K[i](=K_i)$. The vector grading is obtained as follows. Each coefficient of the form vg(i,a) corresponds to having coefficient $a_i = a$ when the vector grading is written as $\sum_{i \in \mathbb{N}} a_i e_i$. The product of vector gradings corresponds to the

sum of the individual gradings. For example vg(2,1)vg(1,-1) corresponds to the vector grading $(-1,1,0,0,0,\ldots)$.

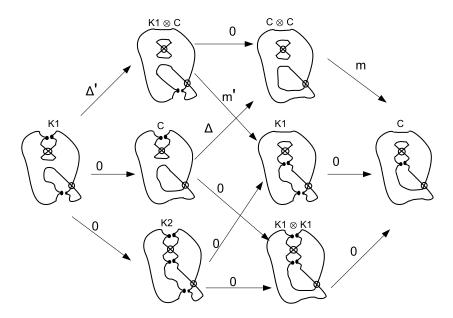


Figure 12: Virtual Knot 3.1 Arrow Polynomial Categorification Complex

We will again omit the proof of invariance under the Reidemeister Moves, which is similar to the equivalent proof for Khovanov homology. Similarly we leave out most of the proof that $d^2 = 0$ other than to point out why we work over \mathbb{Z}_2 . As with Khovanov homology, the proof follows by showing that the differential commutes for every possible face with every possible grading configuration in the cube complex. Much of this is follows from the additivity relations for arrow numbers under resmoothing. However, the face in Figure 13 is an example of a general type necessitating working over \mathbb{Z}_2 .

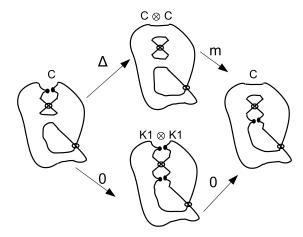


Figure 13: An example of the necessity of working over \mathbb{Z}_2

In [10] a simpler categorification for the arrow polynomial is introduced. We can arrive at this construction through a simple modification of the differential $\tilde{\partial}_{s,s'}$. Suppose we represent the vector grading as $vg(s) = \sum_{i \in \mathbb{N}} a_{i_s} * e_i$ where e_1, e_2, \ldots is the standard basis for \mathbb{R}^{∞} . Rather than preserving the multiple grading and vector grading, $\tilde{\partial}_{s,s'}$ is defined by

$$\tilde{\partial}_{s,s'} = \begin{cases} 1 & \text{, if } a_{1_s} \equiv a_{1_{s'}} \bmod 2 \\ 0 & \text{, if } a_{1_s} \not\equiv a_{1_{s'}} \bmod 2 \end{cases}$$

We have constructed a Mathematica program to calculate all of the categorifications mentioned in this section for knots with at most 6 classical crossings based on Jeremy Green's table [13]. We have been unable to find two virtual knots that are distinguished by the fully-graded categorification and not by the simpler categorification. Additionally, we have no examples of knots which are distinguished from the unknot by the categorification and not by the arrow polynomial.

2.2.1 The Fully-Graded Arrow Categorification and Surface Genus

We may extend Theorem 1.3 on surface genus bounds produced by the arrow polynomial to the fully-graded categorification as follows.

Theorem 2.1. Let K be a virtual knot diagram with fully-graded arrow categorification invariant AKh(K). Suppose that AKh(K) contains a summand having multiple grading \mathcal{M} , a nonempty set of arrow numbers, with $|\mathcal{M}| = n$. Then n determines a lower bound on the genus g of the minimal genus surface in which K embeds. That is, if n = 1 then the minimum genus is at least 1, if n = 2 then the minimum genus is 2 or greater and for $n \geq 3$ if n > 3g - 3 then

s(K) > g.

We add a bit more detail to the earlier sketch to highlight why we only get the extension in the fully-graded categorification. The proof relies on the following fact from [15].

Lemma 2.2. Consider a collection A of non-intersecting essential curves (i.e. not contractible) on an orientable surface S_g of genus g no pair of which cobound an annulus. If g = 1 then $|A| \le 1$ and if $g \ge 2$ then $|A| \le 3g - 3$.

Proof of 2.1: The proof follows by the above lemma once we show that multiple grading corresponds to n non-intersecting essential curves of which no pair co-bound an annulus. Since the multiple grading is an invariant of the knot we have that any embedding into $S_g \times I$ for K must contain a state s with $mg(s) = \mathcal{A}$.

To see that each element of \mathcal{A} is an essential curve suppose for contradiction $K_{i_l} \in \mathcal{A}$ bounds a disk. By the disoriented smoothing relation each cusp in K_{i_l} is paired with another cusp somewhere in s corresponding to the other half of the smoothing. Since K_{i_l} bounds a disk (in the projection to S_g) the Jordan Curve Theorem implies the interior and exterior cusps cannot be paired. If we consider only the internal cusps in K_{i_l} they too cannot be paired with one-another (for odd arrow numbers this follows from parity and for even arrow numbers this follows from orientation.) Thus an inner cusp of K_{i_l} must be paired with the cusp either of another K_{i_j} or of circle with an even number of canceling cusps. In either case we produce another cusps with which to repeat the argument. Since our knot has a finite number of crossing (hence a finite number of cusps) this is a contradiction. A similar argument shows that given $K_{i_l}, K_{i_j} \in \mathcal{A}$ with $i_l \neq i_j$ they cannot co-bound an annulus.

2.3 Categorification and Width

The subject of the width of Khovanov homology for various classes of knots has been of interest since Khovanov's seminal work [26]. Here we produce a definition of width for the virtual setting, recall known results in the classical setting and give some basic results in the virtual knot setting.

In the classical case it was noticed early on that when plotting the homological degree versus the quantum degree for the support of the Khovanov invariant the majority of small knots were supported on 2 diagonals corresponding to the signature of the knot ± 1 . In the classical case we say that a knot is *H-thin* if its Khovanov homology is supported on 2 diagonals corresponding to lines t-2q=constant, else it is called *H-thick*. The thickness of a number of classes of classical knots is known and a recent summary of the known results can be found in [11]. In the case of alternating knots Lee [29] proved that they are

H-thin. Since all alternating knots are of even parity (which we will define shortly), Lee's proof extends to alternating virtual knots as was pointed our by Viro [39].

In the virtual knot setting we need to re-examine our definition of H-thick and H-thin. If we wish to use the thickness of the homology to determine if the Khovanov homology holds additional information over the Jones polynomial we quickly run into trouble in the virtual case. It is no longer enough to determine if the homology is supported on 2 diagonals to determine if the homology contains more information than the polynomial (not to mention that the signature is not

well-defined). For instance virtual knot 2.1 has bracket polynomial

$$(A^4 + A^6 - A^{10})(-A^2 - A^{-2})$$

and Khovanov invariant

$$(q^6 + q^4)t^2 + (q^4 + q^2)t + q^3 + q.$$

By the classical definition virtual knot 2.1 is H-thick as it is supported on 4 diagonals. However, the Khovanov homology does not hold any additional information.

Two good questions to ask are (1) for a given virtual knot, on how many diagonals is the homology $\mathcal{H}(K)$ supported and (2) what is the maximal width between the diagonals (i.e. $c_{max} - c_{min}$ for the supported diagonals t - 2q = c.) We call the solution to the first the *thickness* of the homology and denote it by $Th(\mathcal{H}(K))$ for a given knot K. The second is referred to as the *width* of the homology and denoted by $W(\mathcal{H}(K))$.

More can be said about knots with orientable atoms. We recall from Manturov [33] that for a given knot K, an atom for K is a pair (M,Γ) where M is a surface without boundary (not necessarily connected or orientable) and Γ is a 4-valent graph on M such that (M,Γ) admits a checkerboard coloring. We say an atom is orientable if M is orientable.

In [34] Manturov proves that for knots with orientable atoms we have:

Theorem 2.3. For a knot K with orientable atom, $Th(Kh(K)) \leq g(K) + 2$ where g(K) is the Turaev genus (or atom genus) of the knot.

The proof requires a careful examination of the interplay between the Turaev genus of the knot and the number of crossings in the knot diagram. Note that the orientable condition is important. Virtual knot 2.1 has Th(Kh(K)) = 4 (as shown above), however g(K) = 1/2 since K can be placed on the projective plane in a checkerboard fashion.

Asking the same questions for the fully-graded arrow categorification we immediately see:

Theorem 2.4. Given a virtual knot K suppose the arrow polynomial $\langle K \rangle_A$ contains a monomial with non-zero arrow number $K_{i_1}^{e_1} \dots K_{i_n}^{e_n}$ then

$$W(AKh(K))) \geq 2(\sum_{i=1,\dots,n} e_i)$$

Proof. This is an immediate consequence of categorification. Since we have categorified up to multiple grading and vector grading the monomial with non-zero arrow number $K_{i_1}^{e_1} \dots K_{i_n}^{e_n}$ corresponds to a term in AKh(K). If we consider the vector gradings related to the corresponding unenhanced state in the cube complex we see the the largest and smallest correspond to the "all 1" labeling and the "all X" labeling. The corresponding width between these states is $2(\sum_{i=1,\dots,n} e_i)$ giving the theorem. \blacksquare

The above proof actually gives more if we consider all possible labelings.

Theorem 2.5. Given a virtual knot K suppose the arrow polynomial $\langle K \rangle_A$ contains a monomial with non-zero arrow number $K_{i_1}^{e_1} \dots K_{i_n}^{e_n}$, then

$$Th(AKh(K))) \ge \sum_{i=1,...,n} e_i$$

2.4 Computations and Examples

Inspired by Dror Bar-Natan's program for Khovanov homology [4] we have created a collection of Mathematica programs which calculate the categorifications of the arrow polynomial mentioned above. More information on these programs can be found in the Appendix. The program are also available from the first authors website. The following examples have been computed using the list of knots available at Jeremy Green's Knot Tables [13] as well as those in LinKnot [16].

2.4.1 Identical Khovanov Invariant but Distinguished by a Categorification of the Arrow Polynomial

Example 2.4. Virtual knots 5.129 in Figure 14 and 5.267 in Figure 15 both have Khovanov invariant

$$Kh(5.129) = Kh(5.267) = \frac{1}{q^5t^2} + \frac{1}{q^3t^2} + \frac{1}{q^3t} + q^2t + \frac{1}{q^2} + \frac{1}{qt} + q + \frac{1}{q} + t + 1$$

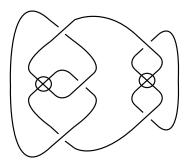


Figure 14: Virtual Knot 5.129

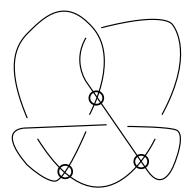


Figure 15: Virtual Knot 5.267

and arrow polynomial

$$AP(5.129) = AP(5.267) = -A^{10} + A^6 - A^4 K 2 - 2A^2 K 1^2 - A^2 K 1 + \frac{K1}{A^2} + 2A^2 - K 2$$
 However,

$$\begin{split} AKh(5.129) &= \frac{vg(2,1)K[2]}{q^3t} + \frac{2vg(1,2)K[1]}{q^3} + q^2tvg(1,-1)K[1] + \frac{vg(1,1)K[1]}{q^2} \\ &+ qtvg(2,-1)K[2] + \frac{vg(2,-1)K[2]}{qt} + \frac{tvg(2,1)K[2]}{q} \\ &+ 2qvg(1,-2)K[1] + tvg(1,1)K[1] + vg(1,-1)K[1] + \frac{4K[1]}{q} \\ &+ \frac{1}{q^5t^2} + \frac{1}{q^3t^2} + \frac{2}{q^3t} + \frac{2}{qt} + qt + \frac{t}{q} + q + \frac{1}{q} \end{split}$$

and

$$\begin{split} AKh(5.267) &= \frac{vg(2,1)K[2]}{q^3t} + \frac{2vg(1,2)K[1]}{q^3} + q^2tvg(1,-1)K[1] + \frac{vg(1,1)K[1]}{q^2} \\ &\quad + qtvg(2,-1)K[2] + \frac{vg(2,-1)K[2]}{qt} + \frac{tvg(2,1)K[2]}{q} \\ &\quad + 2qvg(1,-2)K[1] + tvg(1,1)K[1] + vg(1,-1)K[1] + \frac{4K[1]}{q} \\ &\quad + \frac{1}{q^5t^2} + \frac{1}{q^3t^2} + \frac{2}{q^3t} + \frac{2}{qt} \end{split}$$

2.4.2 Rational Virtual Knots

Lee [29] showed that the Khovanov homology of an alternating knot is completely determined by its Jones polynomial. Recall that every classical rational knot is isotopic to an alternating knot (see Theorem 3.5 of [25]). Hence the Khovanov homology of every classical rational knot is completely determined by its Jones polynomial.

This result of Lee is not the case for virtual knots and the categorifications of the arrow polynomial. The following examples were found with the help of Slavik Jablan and the program LinKnot [16].

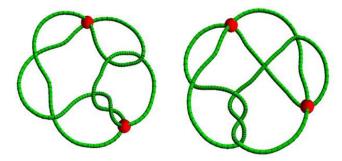


Figure 16: Virtual Knots with Equivalent Polynomials but Distinguished by a Categorification

Both of the knots in Figure 16 have identical normalized bracket polynomial

$$\frac{1}{A^{26}} + \frac{1}{A^{24}} - \frac{1}{A^{20}} - \frac{1}{A^{18}} + \frac{1}{A^{12}} - \frac{1}{A^{10}} - \frac{1}{A^8} - \frac{1}{A^6}$$

and normalized arrow polynomial

$$A^{10} + A^8 \mathrm{K1} - \frac{1}{A^6} - 2A^4 \mathrm{K1} - \frac{\mathrm{K1}}{A^4} + \frac{1}{A^2} + 2 \mathrm{K1}$$

The knot on the left hand side has Khovanov invariant

$$q^{13}t^5 + q^{12}t^4 + q^{11}t^5 + q^{11}t^4 + q^{10}t^4 + 2q^{10}t^3 + q^{9}t^4 + 2q^{8}t^3 + 2q^{8}t^2 + 2q^{6}t^2 + q^{6}t + q^5 + q^4t + q^3$$

and fully-graded arrow categorification invariant

$$\begin{split} q^{12}t^4\mathrm{vg}(1,-1)K[1] + q^{10}t^4\mathrm{vg}(1,1)K[1] \\ + 2q^{10}t^3\mathrm{vg}(1,-1)K[1] + 2q^8t^3\mathrm{vg}(1,1)K[1] \\ + 2q^8t^2\mathrm{vg}(1,-1)K[1] + 2q^6t^2\mathrm{vg}(1,1)K[1] \\ + q^6t\mathrm{vg}(1,-1)K[1] + q^4t\mathrm{vg}(1,1)K[1] + q^{13}t^5 \\ + q^{11}t^5 + q^{11}t^4 + q^9t^4 + q^5 + q^3 \end{split}$$

while the knot on the right hand side has Khovanov invariant

$$q^{13}t^5 + q^{12}t^4 + q^{11}t^5 + q^{11}t^4 + q^{10}t^4 + 2q^{10}t^3 \\ + q^9t^4 + q^9t^3 + q^9t^2 + 2q^8t^3 + 2q^8t^2 + q^7t^3 + 2q^7t^2 + q^7t \\ + 2q^6t^2 + q^6t + q^5t^2 + q^5t + q^5 + q^4t + q^3$$

and fully-graded arrow categorification invariant

$$\begin{split} q^{12}t^4\mathrm{vg}(1,-1)K[1] + q^{10}t^4\mathrm{vg}(1,1)K[1] \\ + 2q^{10}t^3\mathrm{vg}(1,-1)K[1] + 2q^8t^3\mathrm{vg}(1,1)K[1] \\ + 2q^8t^2\mathrm{vg}(1,-1)K[1] + 2q^6t^2\mathrm{vg}(1,1)K[1] \\ + q^6t\mathrm{vg}(1,-1)K[1] + q^4t\mathrm{vg}(1,1)K[1] + q^{13}t^5 \\ + q^{11}t^5 + q^{11}t^4 + q^9t^4 + q^9t^3 + q^9t^2 + q^7t^3 + 2q^7t^2 \\ + q^7t + q^5t^2 + q^5t + q^5 + q^3 \end{split}$$

3 Parity and Virtual Knots

3.1 Parity and the Reidemeister Moves

Given a diagram D for a knot K label each crossing uniquely 1 through n, where n is the total number of crossings in D. Let P an arbitrary base-point on the knot. Starting at P and following the orientation of the knot we can construct a sequence of length 2n with terms corresponding to each crossing we encounter. Each term is a 3-tuple of the form $(O \text{ or } U, \text{ Crossing Number}, \pm)$ where O or U corresponds to an over or under-crossing respectively and \pm corresponds to the sign of the crossing. The resulting code is referred to as the (signed, oriented) $Gauss\ code$ for the diagram D of the knot K.

The Gauss code can be represented diagrammatically as follows. Given a circle (often refereed to as the *core circle*) place upon it in a counterclockwise

fashion 2n points where each point is labeled by a crossing name (an integer between 1 and n) in the cyclic order corresponding to the Gauss code. Between the two occurrences of a crossing on the core circle, place a signed, oriented chord where the sign corresponds to the crossing sign and the orientation goes from the over crossing to the under crossing. We call this the *chord diagram* for D [14], [24]. For example, the knot 3.1 in Figure 7 has Gauss Code

"
$$O1-, O2-, U1-, O3+, U2-, U3+$$
"

and chord diagram as in Figure 17.

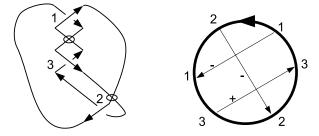


Figure 17: Chord Diagram for Virtual Knot 3.1

Definition 3.1. Given a diagram D for a knot K we can label each crossing as even or odd in the following manner. For each crossing v locate the 2 occurrences of v in the Gauss code for D. If the number of crossing labels between the two occurrences of v is even then label the crossing even. Else it is labeled odd.

Remark 3.1. This parity is well-defined for a 1-component links (i.e. knots) as the number of crossing labels in the Gauss code is 2n where n is the number of crossings.

It is important to notice how parity behaves under the classical Reidemeister moves. Note that virtual Reidemeister moves do not change the Gauss code or chord diagram and thus do not affect parity.

• Reidemeister I

A first Reidemeister move is always even, as is shown in Figure 18



Figure 18: Reidemeister I equivalence for flat chord diagram

• Reidemeister II

The two crossings involved in a second Reidemeister move are either both

even or both odd. To see this, note that in Figure 19 if the number of crossings before the second Reidemeister move is n+2 and a and b denote the number of markings on the core circle as labeled in the figure then a+b=2n is even. Hence either a and b are both even or both odd.

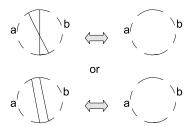


Figure 19: Reidemeister II equivalence for flat chord diagram

• Reidemeister III

In a third Reidemeister move either all crossings are even or two are even and one is odd. To see this note that in Figure 20 if the number of crossings not involved in the third Reidemeister move is n and a, b and c denote the number of markings on the core circle as labeled in the figure then a+b+c=2n is even. Hence either a, b and c are all even or two are odd and one is even.

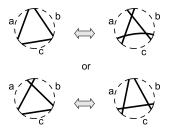


Figure 20: Reidemeister III equivalence for flat chord diagram

3.2 Manturov's Graphical Parity Bracket Polynomial

Manturov [31] introduced the following graphical modification for the bracket polynomial.

Definition 3.2. The parity bracket polynomial of a virtual knot K is defined by the relations in Figure 21.

Definition 3.3. Given a virtual knot K with diagram D, the normalized parity bracket polynomial of K is given by

$$PF_A(K) = PF_A(D) = (-A)^{-3\omega(D)} \langle D \rangle_P$$

Figure 21: Parity Bracket Polynomial Skein Relations

where $\langle D \rangle_P$ is the parity bracket polynomial of D and

 $\omega(D) = writhe(D) = (\# positive crossings in D) - (\# negative crossings in D).$

Theorem 3.1. The parity bracket polynomial is an invariant of virtual knots.

Proof. We give an outline of the proof. The majority of this proof follows from Kauffman's proof of invariance for the bracket polynomial [21]. You can find a similar proof by Manturov in [31].

- 1. Reidemeister I follows from the writhe normalization.
- 2. Reidemeister II follows for even crossing as in the classical case and for odd crossing by the reduction relations.
- 3. Reidemeister III follows by applying the usual trick at a single even crossing. (Note in the mixed case there is only 1 even crossing to choose.)

Example 3.1. Figure 22 displays the calculation of the parity bracket polynomial for virtual knot 3.1 in Figure 7.

Notice that the parity bracket polynomial contains graphical coefficients. Since all of the remaining crossings are virtual or graphical (i.e. coming from an odd crossing) the only skein relations we may apply to the graphical coefficients are the graphical Reidemeister II move as well as the graphical detour move.

3.2.1 The Parity Bracket Polynomial and Surface Genus

Definition 3.4. Given a graphical coefficient D the minimal surface genus s(D) is the minimal genus for an orientable surface S_g such that there is an embedding $D \to S_g$. Given the product of graphical coefficients $D_1D_2 \cdots D_n$ the surface genus $s(D_1D_2 \cdots D_n)$ is the minimal genus for an orientable surface S_g such that there exist disjoint embedding $D_i \to S_g$ for $i \in \{1, \ldots, n\}$.

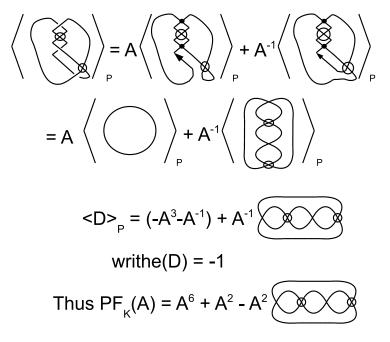


Figure 22: Virtual Knot 3.1 Graphical Parity Bracket Polynomial

Remark 3.2. Note that in the case of the parity bracket polynomial the minimal surface genus for a graphical coefficient is the same as the minimal surface genus for the underlying flat virtual knot. Hence for a graphical coefficient D, $s(D) \geq s(K)$ where K is any virtual knot arising from D by resolving all crossing in any manner.

Theorem 3.2. Given a knot K, the parity bracket polynomial gives a lower bound on the surface genus of K, s(K). More precisely, if $PF_K(A)$ contains a monomial with graphical coefficients $D_1D_2\cdots D_n$ then

$$s(D_1D_2\cdots D_n) \leq s(K)$$

Proof. Suppose K is given by an embedding $S^1 \hookrightarrow S_g \times I$ and s' is the state of the parity bracket polynomial corresponding to the term with graphical coefficients $D_1D_2\cdots D_n$. Projecting s down onto $S_g\times\{0\}$, we see that the minimal surface genus of s' is at least $s(D_1D_2\cdots D_n)$. Since the polynomial is an invariant of the knot this holds for every projection. \blacksquare

Example 3.2. Let K be virtual knot 4.72 in Figure 23. It is a short exercise to show $\langle K \rangle_A = 1$ and that

$$\langle K \rangle_P = -A^4 - A^2 + D_2[1] - 2 - \frac{1}{A^2} - \frac{1}{A^4}$$

where
$$D_2[1] =$$
 Note that $s(D_2[1]) = 1$ [8] and hence $s(K) \ge$

1. Note that the diagram in Figure 23 has genus 2. It is not currently known to us if the minimal surface genus is 1 or 2. Similarly the diagram in Figure 23 has virtual crossing number 3. It is unclear if there is a diagram for this knot with a lower virtual crossing number.

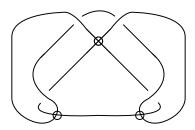


Figure 23: Virtual Knot 4.72

3.3 A Parity Arrow Polynomial

We use Manturov's idea of graphical coefficients [31] to extend the arrow polynomial via parity as follows.

Definition 3.5. The (un-normalized) parity arrow polynomial of a virtual knot K is defined by the relations in Figures 24 and 25. We expand as usual on the even crossing and make a graphical vertex for odd crossings.

Figure 24: Parity Arrow Polynomial Crossing Skein Relations

Definition 3.6. Given a virtual knot K with diagram D, The normalized parity arrow polynomial of K is given by

$$PAP_A(K) = PAP_A(D) = (-A)^{-3\omega(D)} \langle D \rangle_{PA}$$

$$\left\langle \begin{array}{c} \begin{array}{c} \begin{array}{c} \\ \\ \end{array} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} \\ \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} \\ \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\$$

Figure 25: Parity Arrow Polynomial Reduction Skein Relations

where $\langle D \rangle_{PA}$ is the parity arrow polynomial of D and

 $\omega(D) = writhe(D) = (\# positive crossings in D) - (\# negative crossings in D).$

Theorem 3.3. The normalized parity arrow polynomial is an invariant of virtual knots.

Proof. As in the case of the parity bracket polynomial much of the proof is the same as in the non-parity version.

- 1. Reidemeister I follows from the writhe normalization.
- 2. Reidemeister II follows for even crossing by the equivalent proof for the arrow polynomial and for odd crossing by the reduction relations.
- 3. Reidemeister III follows by applying the usual trick at a single even crossing in conjunction with the cusped 'Reidemeister II'-like relation. (Note in the mixed case there is only 1 even crossing to choose.) See Figure 26 for one of diagramatic proofs. The others follow similarly. ■

Example 3.3. The normalized parity arrow polynomial for virtual knot 4.70 in Figure 27 is equal

$$D_2[3]A^8 + 2K_1A^6 - A^6 - A^2$$

where $D_2[3]$ is the graphical coefficient. We should note that the parity bracket polynomial of virtual knot 4.70 also contains a graphical coefficient.

$$\begin{vmatrix} e & & & \\$$

Figure 26: Invariance for one of the mixed Reidemeister III move.

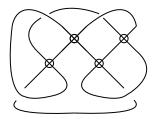


Figure 27: Virtual Knot 4.70

Remark 3.3. In [18] Kauffman introduced a polynomial called with extended bracket polynomial which is a generalization of the arrow polynomial. One key difference between these two polynomials is that the cusps in the extended bracket polynomial are maintained in associated pairs. One can extend the parity arrow polynomial in a similar fashion by replacing the mixed 'Reidemeister II'-like relation with a similar relation $\begin{pmatrix} & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & &$

3.3.1 The Parity Arrow Polynomial and Surface Genus

Similar to the parity bracket polynomial we have the following lower bound on the surface genus.

Theorem 3.4. Given a knot K, the parity bracket polynomial gives a lower bound on the surface genus of K, s(K). More precisely, if $\langle D \rangle_{PA}$ contains a monomial with graphical coefficients $D_1D_2\cdots D_n$ then

$$s(D_1D_2\cdots D_n) \leq s(K)$$

Proof. This is identical to the proof for the parity bracket polynomial.

Example 3.4. Virtual knot 5.5 in Figure 28 has arrow polynomial

$$A^{10}\mathit{K1}^2 - A^{10}\mathit{K1} - 3A^6\mathit{K1}^2 + 3A^6\mathit{K1} + A^6 - \frac{1}{A^6} - 2A^4\mathit{K2} - 3A^2\mathit{K1} + \frac{\mathit{K1}}{A^2} + 2A^2$$

and parity arrow polynomial

$$-A^4D_4[1] - A^6 - 2A^2 - \frac{1}{A^2}$$

Where $D_4[1] = \bigcup_{K \in \mathbb{N}} \mathbb{N}$ Note that by [9] the arrow polynomial gives a minimal surface genus, $s(K) \geq 1$. However, in [8] Dye and Kauffman show that a Kishino knot lying under $D_4[1]$ (in the sense of resolving graphical nodes into knot crossings) has surface genus 2. Hence the parity arrow polynomial gives the lower bound $s(K) \geq 2$.

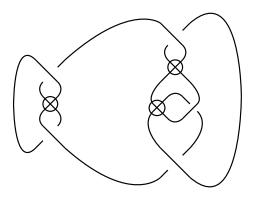


Figure 28: Virtual Knot 5.5

3.4 Z-Equivalence and Graphical Parity Polynomials

When computing the normalized bracket polynomial for virtual knots the relation of Z-Equivalence, depicted in Figure 29, goes undetected. Passing to the parity bracket polynomial we have the option to add the corresponding graphical relation to the coefficients (i.e. including the relation in Figure 29 when the classical crossings are replaced by graphical nodes.) We call the resulting polynomial the z-parity bracket polynomial

Going a step further, we can choose to completely ignore the graphical coefficients by sending the graphical nodes to virtual crossings. This leads to the following forgetful parity bracket polynomial.



Figure 29: Z-Equivalence and the Bracket Polynomial

Lemma 3.5. The parity bracket polynomial is strictly stronger than the z-parity bracket polynomial which in turn is strictly stronger than the forgetful parity bracket polynomial.

Proof. For the parity bracket polynomial and z-parity bracket polynomial the follows immediately from the definition. For the forgetful parity bracket polynomial and z-parity bracket polynomial, notice that the action of swapping an odd crossing for a virtual crossing in the Z-Equivalence relation yields an identity.

3.5 Manturov's Parity Filtration

In [31] Manturov introduced the following descending filtration on the category of virtual knots. Given a virtual knot K with chord diagram D. Let $D_0 = D$ be the equivalence class of D up to Reidemeister moves and define D_{i+1} to be the equivalence class of D_i after removing all odd chords (or equivalently, turning odd crossings into virtual crossings.)

This is well-defined since parity is invariant under the Reidemeister moves as shown above, most notably this filtration does not introduce the forbidden move from Figure 3 when applied to the mixed-parity Reidemeister III move. Hence for 2 representatives $D_i, D_i' \in [D_i] := \text{Equivalence Class of } D_i$ we have $[D_{i+1}] \equiv [D_{i+1}']$.

Diagrammatically this filtration is described by the map sending odd crossing to virtual crossing and hence the forgetful parity polynomials are precisely an application of the respective polynomial on the filtration.

Theorem 3.6. 1. For any virtual knot this filtration is finite. (i.e. there exists n such that $D_n = D_i$ for $n \le i$.)

2. For any classical knot this filtration is of the form $D_0 = D_1 = ...$, that is all levels of the filtration are identical.

Proof. 1. This follows from the finiteness of crossings.

2. Every classical knot is equivalent to a knot with all even crossings. \blacksquare

It is not difficult to construct a family of virtual knots for which given an n, $D_n = D_i$ for $n \leq i$. Consider the family in Figure 30. Here the knot F_1 is the 2-crossing virtual knot (hence not equivalent to the unknot.) Each additional

member of the family is produced from its predecessor by the addition of two odd positive crossing arcs and which become the only odd arcs in the new diagram. Since we are unable to cancel the two new odd crossings with one another we see each new virtual knot created in this way is unique from its predecessor. Moreover for F_n it is easy to verify that for $D_n = D_i = \text{Unknot}$ for $n \leq i$.

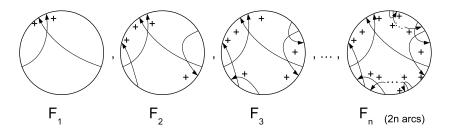


Figure 30: A Parity Filtration Family

3.6 Extending the Parity Polynomials to Links

For this subsection we will take a wider view and consider the space of virtual links (2 or more components). One should note that our definition of even and odd parity does not naturally extend. For example, the links in Figure 31 illustrate some of the difficulty in the natural extension.



Figure 31: Examples of Difficulty in Extending the Definition to Links

Omitting signs, the left link in 31 has Gauss code "O1, U1, O2; U2" while the other has Gauss code "U1; O1, O2; U2". In the first of these Crossing 1 is both even and odd in the first component while Crossing 1 is either even or odd depending upon whether you examine the first or second link component.

We may circumvent this pitfall by defining even and odd for self-crossings based on the parity of self-crossing in each component while labeling crossings shared by 2 components as link crossings.

Example 3.5. The link in Figure 32 has Gauss code

"O1, O7, O3, U1, U2, U3, O2; U4, O5, U6, U5, O4, O6, U7"

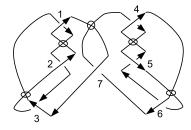


Figure 32: Link Parity Crossing Labelings

Crossings 1, 2, 4 and 5 are odd, crossings 3, and 6 are even and crossing 7 is a link crossing.

As we did with odd crossings, we investigate the invariance of crossings between links to provide the framework for generalizing the parity polynomials. We will call a crossing where both arcs involved are in the same link component a self-crossing while a crossing whose arcs are in separate components a link-crossing.

• Reidemeister I

In a Reidemeister I move only a single link component is involved hence is always an even self-crossing.

• Reidemeister II

The two arcs involved in a second Reidemeister move are either both in the same component or each is in a different component. Thus either both crossings above are self-crossings or both crossings are link-crossings.

• Reidemeister III

In a third Reidemeister move either all strands involved are in one component, or two in one component and one in another or all three in separate components. Thus either all crossings are self-crossings, or one self-crossing and two link-crossings or three link-crossings respectively.

This motivates the following definitions for link parity polynomials.

Definition 3.7. Given a diagram D for a virtual knot K the (link) parity bracket polynomial of K is defined by the relations in Figures 33 and 34.

Figure 33: Link Parity Bracket Polynomial Smoothing Relations

$$\langle \bigcirc \sqcup \mathsf{K} \rangle_{\mathsf{P}} = (-\mathsf{A}^{2} - \mathsf{A}^{-2}) \langle \mathsf{K} \rangle_{\mathsf{P}}$$

$$\langle \bigcirc \mathsf{M} \rangle_{\mathsf{P}} = \langle \bigcirc \mathsf{M} \rangle_{\mathsf{P}}$$

$$\langle \bigcirc \mathsf{M} \rangle_{\mathsf{P}} = \langle \bigcirc \mathsf{M} \rangle_{\mathsf{P}}$$

$$\langle \bigcirc \mathsf{M} \rangle_{\mathsf{P}} = \langle \bigcirc \mathsf{M} \rangle_{\mathsf{P}}$$

Figure 34: Link Parity Bracket Polynomial Reduction Relations

Definition 3.8. Given a virtual link K with diagram D, The normalized (link) parity bracket polynomial of K is given by

$$PF_A(K) = PF_A(D) = (-A)^{-3\omega(D)} \langle D \rangle_P$$

where $\langle D \rangle_P$ is the parity bracket polynomial of D and

 $\omega(D) = writhe(D) = (\# positive crossings in D) - (\# negative crossings in D).$

Theorem 3.7. The (link) parity bracket polynomial is an invariant of virtual knots.

- *Proof.* 1. **RI:** A crossing involved in a Reidemeister I move is always an even self-crossing, hence invariance follows from the writhe normalization as in the normalized bracket polynomial.
 - 2. RII: Reidemeister II follows for even self-crossing as in the classical case and for odd self-crossing and link-crossings by the reduction relations.

- 3. RIII: Here we have three cases to consider:
 - (a) Reidemeister III for three self-crossings follows by applying the usual trick at a single even crossing.
 - (b) For a Reidemeister III involving one self-crossings and two link crossings, if the self-crossing is even then the usual trick with the RII-like move for link crossings gives invariance. If the self-crossing is odd then the result is immediate by the reduction relations.
 - (c) Reidemeister II for three link-crossings also follows immediately from the reduction relations.
- 4. **Mixed Move:** For an even self-crossing this is the standard proof and for an odd self-crossing or link-crossing it follows from the reduction relations.

Example 3.6. Figure 35 displays the calculation for the (link) parity bracket polynomial for the given 2-component link.

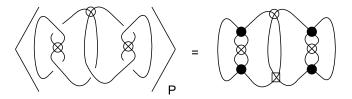


Figure 35: Graphical Link Parity Bracket Polynomial Example

Similarly for the parity arrow polynomial we have:

Definition 3.9. Given a diagram D for a virtual link K the (link) parity arrow polynomial of K is defined by the relations in Figures 33 and 34.

Definition 3.10. Given a virtual link K with diagram D, The normalized (link) parity arrow polynomial of K is given by

$$PAP_A(K) = PAP_A(D) = (-A)^{-3\omega(D)} \langle D \rangle_{PA}$$

where $\langle D \rangle_{PA}$ is the parity arrow polynomial of D and

 $\omega(D) = writhe(D) = (\# positive crossings in D) - (\# negative crossings in D).$

Theorem 3.8. The (link) parity arrow polynomial is an invariant of virtual knots.

Figure 36: Link Parity Arrow Polynomial Smoothing Relations

$$\left\langle \begin{array}{c} \begin{array}{c} \\ \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA}$$

$$\left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA}$$

$$\left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA}$$

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$$\left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA}$$

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$$\left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA}$$

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$$\left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \\ \end{array} \right\rangle_{PA} = \left\langle \begin{array}{c} \\ \end{array} \right\rangle_{PA$$

Figure 37: Link Parity Arrow Polynomial Reduction Relations

Proof. This proof is nearly identical to the one above. The only difference is the proof for the Reidemeister III move involving an even self-crossing and two link crossings. Here we use a cusped RII-like move for link crossing in the usual trick for RIII invariance. ■

Remark 3.4. We have used a similar extension to links in [17] to generalize the construction of Parity Biquandles.

4 Parity and Categorifications

We would like to categorify the parity polynomials in an analogous manner to the original polynomials by adding an additional grading, similarly to the construction of the categorification of the arrow polynomial, based on the equivalence classes of graphified flat knot diagrams. However, it is fairly simple to construct an example showing this to be naive. For instance, consider the virtual knot in Figure 38.

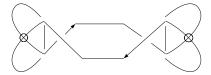


Figure 38: Kishino Knot

Performing the available Reidemeister II move, the resulting diagram is one of three virtual knots often referred to as Kishino knots. Figure 39 shows that both the parity bracket polynomial and parity arrow polynomial of the knot is the graphified version of the diagram as there are no graphical Reidemeister II moves or detour moves available.

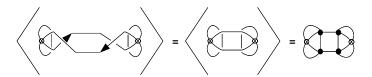


Figure 39: Graphical Parity Bracket Polynomial of a Kishino Knot

However, when we consider the Khovanov complex (the arrow polynomial categorifications have equivalent complexes) as in Figure 40 we can see that $d^2 \neq 0$. In particular, the all-A and all- A^{-1} states are both graphically equivalent to two circles while in the middle we have the top state graphically equivalent to a graphified Kishino knot and the bottom state graphically equivalent to

3 circles. Hence, as shown in the figure, the upper differentials are both the 0-map. Considering the element $(x \otimes 1)$, we see

$$d^2(x \otimes 1) = (1 \otimes m) \circ (\Delta \otimes 1)(x \otimes 1) = (1 \otimes m)(x \otimes x \otimes 1) = x \otimes x \neq 0$$

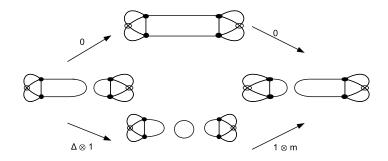


Figure 40: Graphical Parity Kishino Complex

However, this does not prevent us from applying Manturov's parity filtration along with the forgetful version of the parity categorifications. In doing so we clearly lose some of the power of the parity polynomial (for instance the Kishino knot is no longer detected) but we still retain an invariant which is capable of detecting non-classicality. We can define the parity Khovanov homology (respectively, parity arrow categorification) to be the homology theory produced by first applying Manturov's parity filtration to the given knot and then computing the Khovanov homology (respectively, the arrow categorification) of the resulting knot. Similarly, define the parity Khovanov invariant (respectively, parity arrow invariant) to be the resulting Poincaré polynomial as produced previously.

For instance, consider the knot in Figure 41. Applying the parity Khovanov homology we have that the original knot has Khovanov invariant

$$\frac{1}{q^9t^3} + \frac{1}{q^8t^2} + \frac{1}{q^7t^3} + \frac{1}{q^7t^2} + \frac{1}{q^6t^2} + \frac{1}{q^6t} + \frac{1}{q^5t^2} + \frac{1}{q^5} + \frac{1}{q^4t} + \frac{1}{q^3}$$

Applying the filtration and turning crossings 1 and 4 into virtual crossings we have that the underlying knot at this level of the filtration is the two crossing virtual knot. Hence virtual knot 4.9 has parity Khovanov invariant

$$\frac{1}{q^6t^2} + \frac{1}{q^4t^2} + \frac{1}{q^4t} + \frac{1}{q^3} + \frac{1}{q^2t} + \frac{1}{q}$$

and moreover is non-classical.

Using Jeremy Green's virtual knot table [13] we have been able to calculate the parity categorifications on knots with at most 6 real crossings. Table 1 is a collection of planar diagram codes for 8 knots which are not distinguished

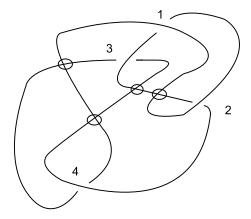


Figure 41: Virtual Knot 4.9

from the unknot via the bracket polynomial, arrow polynomial or their categorifications, but are distinguished from the unknot via the parity arrow categorification. Please see the Appendix for an explanation of our planar diagram conventions. The top four knots have parity arrow invariant

$$\frac{\operatorname{vg}(2,1)K[2]}{q^3t} + \frac{\operatorname{vg}(1,2)K[1]}{q^3} + \frac{\operatorname{vg}(2,-1)K[2]}{qt} + q\operatorname{vg}(1,-2)K[1] + \frac{2K[1]}{q}$$

while the lower four have parity arrow invariant

$$q^3t \text{vg}(2,-1)K[2] + q^3 \text{vg}(1,-2)K[1] + qt \text{vg}(2,1)K[2] + \frac{\text{vg}(1,2)K[1]}{q} + 2qK[1]$$

4.1 Link Parity Polynomials and Categorification

Following the construction presented in Section 3.6 we can extend the graphical polynomials to links. However, the graphical coefficients for links suffer a similar problem to that of knots when categorified. As with knots we map use the forgetful map to send the graphical link coefficients to virtual crossings. The effect of this for links is rather unfortunate as it reduces a link to the disjoint union of its components. (This is easiest to see by thinking of the chord diagram.) Hence it reduces the link parity categorification back to the knot parity categorification setting.

4.2 Intriguing Examples

Using Jeremy Green's tables [13] we have calculated the above invariants as along with the Sawollek polynomial and z-parity Sawollek polynomial([17]) for knots with at most 6 real crossings. The knots in Figure 42 and Figure 43

6.5508	PD[X[4, 2, 5, 1], X[7, 4, 8, 3], X[10, 6, 11, 5], Y[12, 3, 1, 2],
	Y[9, 7, 10, 6], Y[8, 12, 9, 11]]
6.5627	PD[X[4, 2, 5, 1], X[7, 4, 8, 3], X[10, 6, 11, 5], Y[12, 3, 1, 2],
	Y[9, 7, 10, 6], Y[11, 9, 12, 8]]
6.7613	PD[X[4, 2, 5, 1], X[7, 4, 8, 3], X[9, 7, 10, 6], Y[12, 3, 1, 2],
	Y[10, 6, 11, 5], Y[8, 12, 9, 11]]
6.7701	PD[X[4, 2, 5, 1], X[7, 4, 8, 3], X[9, 7, 10, 6], Y[12, 3, 1, 2],
	Y[10, 6, 11, 5], Y[11, 9, 12, 8]
6.24828	PD[X[6, 4, 7, 3], X[9, 5, 10, 4], X[11, 8, 12, 7], Y[12, 3, 1, 2],
	Y[1, 11, 2, 10], Y[8, 6, 9, 5]
6.37012	PD[X[6, 4, 7, 3], X[8, 6, 9, 5], X[11, 8, 12, 7], Y[12, 3, 1, 2],
	Y[1, 11, 2, 10], Y[9, 5, 10, 4]
6.60677	PD[X[3, 7, 4, 6], X[9, 5, 10, 4], X[11, 8, 12, 7], Y[12, 3, 1, 2],
	Y[1, 11, 2, 10], Y[8, 6, 9, 5]
6.65816	PD[X[3, 7, 4, 6], X[8, 6, 9, 5], X[11, 8, 12, 7], Y[12, 3, 1, 2],
	Y[1, 11, 2, 10], Y[9, 5, 10, 4]

Table 1: Undistinguished from Unknot by Categorification but Distinguished by Parity

are special in that they are not distinguished from the unknot via any of the invariants. Knot 6.32008 has 4 odd crossings while Knot 6.73583 has no odd crossings and both knots are trivial as flats. Using a 2-cable Jones polynomial calculator adapted from Dror Bar-Natan's "faster" Jones polynomial Calculator [3] we have been able to distinguish each of these knots from one-another and from the unknot.

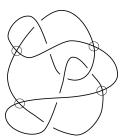


Figure 42: Knot 6.32008

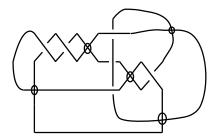


Figure 43: Knot 6.73583

A Appendix

A.1 Computational Results

A.1.1 Planar Diagram Conventions

The following examples and programs compute the associated invariant based on a planar diagram code for a diagram for the given knot whose arcs have been consecutively labeled. Our conventions are listed in Figure 44.

$$= X[i,j,k,l]$$

$$= X[i,j,k,l]$$

$$= Y[i,j,k,l]$$

Figure 44: Planar Diagram Code Conventions

Example A.1. Virtual knot 3.1 as labeled in Figure 45 has planar diagram code:

$$PD[X[1,5,2,4], X[5,4,6,3], Y[6,3,1,2]]$$

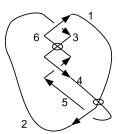
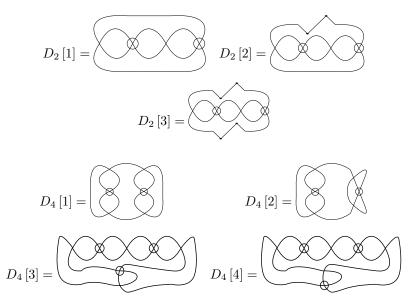


Figure 45: Virtual Knot 3.1

A.1.2 Parity Polynomials

The following table displays the parity bracket polynomial and parity arrow polynomial for virtual knots with at most four crossings. Naming conventions are as in [13]. Graphical coefficients are labeled by D_2 [1], D_2 [2], D_2 [3] and D_4 [1],..., D_4 [4] corresponding to the following diagrams.



It has been shown by Dye and Kauffman (Theorem 4.1 of [8]) that graphical coefficients D_4 [1] and D_4 [2] have surface genus $s(D_4$ [1]) = 2 and $s(D_4$ [2]) = 2. Using this fact we can see that the parity polynomials are able to give a better bound on the genus than that of the arrow polynomial [9] for certain knots. In particular we have $s(K) \ge 2$ for $K \in \{4.1, 4.2, 4.4, 4.5, 4.7, 4.8, 4.55, 4.56, 4.76, 4.77\}.$

Table 2: Parity Bracket and Parity Arrow Polynomial Calculations

Knot	Parity Bracket	Parity Arrow
2.1	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
3.1	$A^{6} - D_{2}[1]A^{2} + A^{2}$	$A^{6} - D_{2}[1]A^{2} + A^{2}$
3.2	$-A^2 - \frac{1}{A^2}$	
3.3	$A^{6} - D_{2}[1]A^{2} + A^{2}$	$ \begin{array}{c c} -A^2 - \frac{1}{A^2} \\ A^6 - D_2[1]A^2 + A^2 \end{array} $
3.4	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
3.5	$ \begin{array}{c} -\frac{D_2[1]}{A^2} + \frac{1}{A^2} + \frac{1}{A^6} \\ A^{18} - A^{10} - A^6 - A^2 \end{array} $	$\begin{array}{c} -\frac{D_2[1]}{A^2} + \frac{1}{A^2} + \frac{1}{A^6} \\ K_1^2 A^{14} - A^{14} - K_1^2 A^{10} - A^2 \end{array}$
3.6	$A - A - A - A$ $A^{18} - A^{10} - A^6 - A^2$	$A^{18} - A^{10} - A^6 - A^2$
3.7	A - A - A - A	$ \begin{vmatrix} A - A - A - A \\ -A^{10} + K_1^2 A^6 - A^6 - K_1^2 A^2 \end{vmatrix} $
4.1	$-A^2 - \frac{1}{A^2}$ $D_4[1]$	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
4.1	D ₄ [1]	$\begin{array}{c c} D_4[1] \\ D_4[2] \end{array}$
4.3	$ \begin{array}{c c} D_4[2] \\ -A^2 - \frac{1}{A^2} \end{array} $	$ \begin{array}{c c} D4[2] \\ -A^2 - \frac{1}{A^2} \end{array} $
4.4	$\begin{array}{c} -A - \frac{1}{A^2} \\ D_4[1] \end{array}$	$\begin{array}{c c} -A & -\frac{A}{A^2} \\ D_4[1] \end{array}$
4.4	D ₄ [1]	$\begin{array}{c} D_4[1] \\ D_4[2] \end{array}$
4.6	$ \begin{array}{c c} D_4[2] \\ -A^2 - \frac{1}{A^2} \end{array} $	$ \begin{array}{c c} D4[2] \\ -A^2 - \frac{1}{A^2} \end{array} $
4.0	$\begin{array}{c c} -A & -\frac{A}{A^2} \\ D_4[2] & \end{array}$	$\begin{array}{c c} -A & -\frac{A}{A^2} \\ D_4[2] & \end{array}$
4.8	$D_4[2]$ $D_4[1]$	$D_4[2]$ $D_4[1]$
4.9	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$
4.10	112 16 14 12	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$
4.11	A - A - A - A $A - A^2 + D_0[1] - 2 - \frac{1}{2} - \frac{1}{2}$	$-K_1A + K_1A - A - A$ $K_1A^2 - A^2 + D_2[3] + K_1 - 1$
4.11	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c} K_1A^2 - A^2 + D_2[3] + \frac{K_1}{A^2} - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \\ \frac{2K_1}{A^6} + \frac{D_2[2]}{A^8} - \frac{1}{A^2} - \frac{1}{A^6} \\ -K_1A^{10} + K_1A^6 - A^6 - A^2 \end{array}$
4.13	$-4^2 - \frac{\overline{A^2}}{1}$	$-\Lambda^2 - \frac{1}{\Lambda^2}$
4.14	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
4.15	$\frac{A^8}{A^{12}} = \frac{A^2}{A^2} = \frac{A^4}{A^4} = \frac{A^6}{A^8} = \frac{A^8}{A^8}$	$A^{6} + A^{8} - A^{2} - A^{6}$ $-K \cdot A^{10} + K \cdot A^{6} - A^{6} - A^{2}$
4.16	$\begin{array}{c} D_{2}[1]A^{8} - 2A^{8} - A^{6} - 2A^{4} - A^{2} \\ -A^{4} - A^{2} + D_{2}[1] - 2 - \frac{1}{A^{2}} - \frac{1}{A^{4}} \\ -A^{2} - \frac{1}{A^{2}} \\ -A^{4} - A^{2} + D_{2}[1] - 2 - \frac{1}{A^{2}} - \frac{1}{A^{4}} \end{array}$	$D_2[2]A^8 + 2K_1A^6 - A^6 - A^2$
4.17	$-A^4 - A^2 + D_2[1] - 2 - \frac{1}{1} - \frac{1}{1}$	$K_1 A^2 - A^2 + D_2[3] + \frac{K_1}{2} - \frac{1}{2}$
4.18	$A^2 - \frac{1}{A^2}$	$K_1A^2 - A^2 + D_2[3] + \frac{K_1}{A^2} - \frac{1}{A^2}$ $-A^2 - \frac{1}{A^2}$
4.19	$A^2 - A^4 - A^2 + D_2[1] - 2 - \frac{1}{2} - \frac{1}{2}$	$K_{\star} A^{2} = A^{2} + D_{a}[9] + \frac{K_{1}}{4} = \frac{1}{4}$
4.20	$\begin{bmatrix} -1 & 1 & D_2[1] & 2 & A^2 & A^4 \\ -1 & -1 & -1 & +1 & 1 \end{bmatrix}$	$\frac{K_1}{K_1} - \frac{K_1}{K_1} - \frac{1}{K_1} - \frac{1}{K_1}$
4.21	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
4.21	$\frac{A_8}{1} - \frac{A_2}{1} - \frac{A_4}{1} - \frac{A_6}{1} - \frac{A_8}{1}$	$\frac{A_6}{K_1} + \frac{A_8}{K_1} - \frac{A_2}{A^2} - \frac{A_6}{A^6}$
4.23		$\frac{1}{4^{6}} - \frac{10}{4^{10}} - \frac{10}{4^{2}} - \frac{10}{4^{6}}$
4.24		$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
4.25	$ \begin{array}{c c} -\frac{1}{A^2} - \frac{1}{A^4} - \frac{1}{A^6} + \frac{1}{A^{12}} \\ -A^2 - \frac{1}{A^2} \end{array} $	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
4.26	$\begin{array}{c c} -A & -\frac{1}{A^2} \\ D_4[3] \end{array}$	$\begin{array}{c c} -A & -\frac{A}{A^2} \\ D_4[3] & \end{array}$
4.27	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.28	$\begin{array}{c c} -A & -\frac{1}{A^2} \\ D_4[4] & \end{array}$	$\begin{array}{c c} -A & -\frac{1}{A^2} \\ D_4[4] & \end{array}$
4.29	$D_2[1]A^8 - 2A^8 - A^6 - 2A^4 - A^2$	$D_2[3]A^8 + 2K_1A^6 - A^6 - A^2$
4.30	$-A^4 - A^2 + D_2[1] - 2 - \frac{1}{1} - \frac{1}{1}$	$K_1 A^2 - A^2 + D_2[2] + \frac{K_1}{4} - \frac{1}{4}$
4.31	$-A^{4} - A^{2} + D_{2}[1] - 2 - \frac{1}{A^{2}} - \frac{1}{A^{4}}$ $A^{12} - A^{6} - A^{4} - A^{2}$	$\begin{array}{c} K_1A^2 - A^2 + D_2[2] + \frac{K_1}{A^2} - \frac{1}{A^2} \\ -K_1A^{10} + K_1A^6 - A^6 - A^2 \end{array}$
4.32	$-A^2 - \frac{1}{12}$	$-A^2 - \frac{1}{A^2}$
4.33	$-A^4 - A^2 + D_2[1] - 2 - \frac{1}{A^2} - \frac{1}{A^4}$	$K_1A^2 - A^2 + D_2[2] + \frac{K_1}{A^2} - \frac{1}{A^2}$
4.34	$\frac{D_2[1]}{A^8} - \frac{1}{A^2} - \frac{2}{A^4} - \frac{1}{A^6} - \frac{2}{A^8}$	$ \frac{2K_1 + \frac{D_2[2]}{A_1^6} + \frac{D_2[2]}{A_1^6} - \frac{1}{A_2^6} - \frac{1}{A_1^6} }{\frac{A_1^6}{A_1^6} + \frac{D_2[2]}{A_1^6} - \frac{1}{A_1^6} } $
4.35	$-A^{8} - A^{2} - A^{4} - A^{6} - A^{8}$ $-A^{2} - A^{2}$	$-A^{6} + \frac{1}{A^{8}} - \frac{1}{A^{2}} - \frac{1}{A^{6}}$
4.36	1 1 1 . 1	$\frac{K_1}{A^6} - \frac{K_1}{A^{10}} - \frac{1}{A^2} - \frac{1}{A^6}$
4.00	$-\frac{1}{A^2} - \frac{1}{A^4} - \frac{1}{A^6} + \frac{1}{A^{12}}$	$\frac{1}{A^6} - \frac{1}{A^{10}} - \frac{1}{A^2} - \frac{1}{A^6}$

	Parity Bracket	Darity Arrow
Knot	Parity Bracket $A^{12} - A^6 - A^4 - A^2$	Parity Arrow
4.37	A - A - A - A	$ \begin{array}{c} -K_1 A^{10} + K_1 A^6 - A^6 - A^2 \\ -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \end{array} $
4.38	$ \begin{array}{c c} -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \end{array} $	$-A^{-} - \frac{-}{A^{2}}$
4.39	$-A^{2} - \frac{1}{A^{2}}$	$-A^2 - \frac{1}{A^2}$
4.40	$\frac{-\frac{1}{A^2} - \frac{1}{A^4} - \frac{1}{A^6} + \frac{1}{A^{12}}}{A^{12} - A^6 - A^4 - A^2}$	$\begin{array}{c} -A - \frac{A^2}{A^2} \\ \frac{K_1}{A^6} - \frac{K_1}{A^{10}} - \frac{1}{A^2} - \frac{1}{A^6} \\ -K_1A^{10} + K_1A^6 - A^6 - A^2 \end{array}$
4.41		$-K_1A^{10} + K_1A^{0} - A^{0} - A^{2}$
4.42	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.43	$ \begin{array}{c} -A^2 - \frac{A^2}{4^2} \\ -A^2 - \frac{1}{A^2} \end{array} $	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
4.44	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.45	$D_4[3]$	$ \begin{array}{c c} D_4[3] \\ -A^2 - \frac{1}{A^2} \end{array} $
4.46	$ \begin{array}{c} D_{4}[3] \\ -A^{2} - \frac{1}{A^{2}} \end{array} $	$-A^2 - \frac{1}{A^2}$
4.47	$ D_4 4 $	$D_4[4]$
4.48	$D_2[1]A^8 - 2A^8 - A^6 - 2A^4 - A^2$	$D_2[2]A^8 + 2K_1A^6 - A^6 - A^2$
4.49	$-A^{4} - A^{2} + D_{2}[1] - 2 - \frac{1}{A^{2}} - \frac{1}{A^{4}}$ $A^{12} - A^{6} - A^{4} - A^{2}$	$\begin{array}{c} K_1A^2 - A^2 + D_2[3] + \frac{K_1}{A^2} - \frac{1}{A^2} \\ -K_1A^{10} + K_1A^6 - A^6 - A^2 \end{array}$
4.50	$A^{12} - A^6 - A^4 - A^2$	$-K_1A^{10} + K_1A^6 - A^6 - A^2$
4.51	$\begin{array}{c} -A^2 - \frac{1}{A^2} \\ \frac{D_2[1]}{A^8} - \frac{1}{A^2} - \frac{2}{A^4} - \frac{1}{A^6} - \frac{2}{A^8} \\ -A^2 - \frac{1}{A^2} \end{array}$	$ \begin{array}{c c} -A^2 - \frac{1}{A^2} \\ \frac{2K_1}{A^6} + \frac{D_2[2]}{A^8} - \frac{1}{A^2} - \frac{1}{A^6} \\ -A^2 - \frac{1}{A^2} \end{array} $
4.52	$\frac{D_2[1]}{A^8} - \frac{1}{A^2} - \frac{2}{A^4} - \frac{1}{A^6} - \frac{2}{A^8}$	$\frac{2K_1}{A6} + \frac{D_2[2]}{A8} - \frac{1}{A2} - \frac{1}{A6}$
4.53	$-A^2 - \frac{1}{4^2}$	$-A^2 - \frac{1}{A^2}$
4.54	$-A^2 - \frac{A^2}{A^2}$	$-A^2 - \frac{A^2}{A^2}$
4.55	$D_4[1]$	D ₄ [1]
4.56	$D_4[2]$	$D_4[2]$
4.57	$D_2[1]A^8 - 2A^8 - A^6 - 2A^4 - A^2$	$D_2[3]A^8 + 2K_1A^6 - A^6 - A^2$
4.58	$-A^4 - A^2 + D_2[1] - 2 - \frac{1}{4^2} - \frac{1}{4^4}$	$K_1A^2 - A^2 + D_2[2] + \frac{K_1}{4^2} - \frac{1}{4^2}$
4.59	$-A^{4} - A^{2} + D_{2}[1] - 2 - \frac{1}{A^{2}} - \frac{1}{A^{4}}$ $-A^{4} - A^{2} + D_{2}[1] - 2 - \frac{1}{A^{2}} - \frac{1}{A^{4}}$	$K_1A^2 - A^2 + D_2[2] + \frac{K_1}{A^2} - \frac{1}{A^2}$ $K_1A^2 - A^2 + D_2[2] + \frac{K_1}{A^2} - \frac{1}{A^2}$
4.60	$-\frac{1}{2} - \frac{1}{4} - \frac{1}{2} + \frac{1}{4}$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
4.61	$ \frac{-\frac{1}{A^2} - \frac{1}{A^4} - \frac{1}{A^6} + \frac{1}{A^{12}}}{A^{12} - A^6 - A^4 - A^2} $	$-K_1A^{10} + K_1A^6 - A^6 - A^2$
4.62		$-A^2 - \frac{1}{12}$
4.63	$ \begin{array}{c} -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \end{array} $	$ \begin{array}{c c} -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \end{array} $
4.64	$\frac{A^2}{-\frac{1}{2} - \frac{1}{2} - \frac{1}{2} + \frac{1}{2}}$	$\frac{K_1}{K_1} - \frac{K_1}{K_1} - \frac{1}{K_1} - \frac{1}{K_1}$
4.65	$-\frac{1}{A^2} - \frac{1}{A^4} - \frac{1}{A^6} + \frac{1}{A^{12}}$ $A^{12} - A^6 - A^4 - A^2$	$\begin{array}{c c} \frac{K_1}{A^6} - \frac{K_1^{A^2}}{A^{10}} - \frac{1}{A^2} - \frac{1}{A^6} \\ -K_1 A^{10} + K_1 A^6 - A^6 - A^2 \end{array}$
4.66	A - A - A - A	$-K_1A + K_1A - A - A$
4.67	$ \begin{array}{c} -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \end{array} $	$ \begin{array}{c c} -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \end{array} $
4.68	$\frac{-A}{1} - \frac{A^2}{A^2}$	$-A - \frac{A}{A^2}$ $K_1 K_1 1 1$
4.69	$\frac{-\frac{1}{A^2} - \frac{1}{A^4} - \frac{1}{A^6} + \frac{1}{A^{12}}}{A^{12} - A^6 - A^4 - A^2}$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
4.69	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$-\mathbf{R}_1A + \mathbf{R}_1A - A - A$ $-\mathbf{R}_2A^8 + 2\mathbf{K}_2A^6 - A^6 - A^2$
4.70	$D_2[1]A^8 - 2A^8 - A^6 - 2A^4 - A^2$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
	$-A^{4} - A^{2} + D_{2}[1] - 2 - \frac{1}{A^{2}} - \frac{1}{A^{4}}$ $-A^{4} - A^{2} + D_{2}[1] - 2 - \frac{1}{A^{2}} - \frac{1}{A^{4}}$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
4.72	$-A^4 - A^2 + D_2[1] - 2 - \frac{1}{A^2} - \frac{1}{A^4}$	$ K_1 A - A^2 + D_2[2] + \frac{-1}{A^2} - \frac{1}{A^2} $
4.73	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$-A - \overline{A^2}$
4.74	$-A - \frac{A^2}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.75	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.76	D ₄ [2]	$D_4[2]$
4.77	D ₄ [1]	D ₄ [1]
4.78	$A^{12} - A^6 - A^4 - A^2$	$-K_1A^{10} + K_1A^6 - A^6 - A^2$
4.79	$A^{12} - A^6 - A^4 - A^2$	$-K_1A^{10} + K_1A^6 - A^6 - A^2$
4.80	$D_4[3]$	$D_4[3]$
4.81	$D_4[4]$	$D_4[4]$
4.82	$-A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$	$-A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$

Knot	Parity Bracket	Parity Arrow
4.83	$-A^{2} - \frac{1}{A^{2}}$ $-A^{10} + D_{2}[1]A^{6} - A^{6} - D_{2}[1]A^{2}$	$-A^2 - \frac{1}{A^2}$
4.84	$-A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$	$-A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$
4.85	$-A^2 - \frac{1}{A^2}$	$A^{10} + K_1^2 A^6 - A^6 - K_1^2 A^2$
4.86	$-A^{10} - \frac{1}{A^{10}} - A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$	$-A^{10} - A^2 + \frac{K_1^2}{A^2} - \frac{1}{A^2} - \frac{K_1^2}{A^6} + \frac{1}{A^6} -A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$
4.87	$-A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$	$-A^{10} + D_2[1]A^{6} - A^{6} - D_2[1]A^{2}$
4.88	$ -A^{10} + D_2 1 A^{0} - A^{0} - D_2 1 A^{2}$	$-A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$
4.89	$A^{18} - A^{10} - A^6 - A^2$	$-A^{18} + 2K_1^2A^{14} - 2A^{14} - 2K_1^2A^{10} +$
		$A^{10} + A^6 - A^2$
4.90	$-A^{10} - \frac{1}{A^{10}}$	$-K_1^2A^6 + A^6 + K_1^2A^2 - 2A^2 + \frac{K_1^2}{A^2}$
		$ \frac{\frac{2}{A^2} - \frac{K_1^2}{A^6} + \frac{1}{A^6}}{-A^2 - \frac{1}{A^2}} $
4.91	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.92	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.93	$-A^{2} - \frac{1}{A^{2}}$ $-A^{2} - \frac{1}{A^{2}}$ $-A^{10} + D_{2}[1]A^{6} - A^{6} - D_{2}[1]A^{2}$	$ \begin{array}{c c} -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \\ -A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2 \end{array} $
4.94	$-A^2 - \frac{1}{4^2}$	$-A^2 - \frac{1}{A^2}$
4.95	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.96	$A^{10} + D_{2}[1]A^{6} - A^{6} - D_{2}[1]A^{2}$	$-A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$
4.97	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.98	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.99	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
4.100	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.101	$-A^2 - \frac{1}{A^2}$	$ \begin{array}{c c} -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \end{array} $
4.102	$-A^2 - \frac{1}{A^2}$	$-A^2 - \frac{1}{A^2}$
4.103	$ -A^{10} + D_2 1 A^{0} - A^{0} - D_2 1 A^{2}$	$-A^{10} + D_2[1]A^6 - A^6 - D_2[1]A^2$
4.104	$ \begin{array}{c} -A^2 - \frac{1}{A^2} \\ A^{18} - A^{10} - A^6 - A^2 \end{array} $	$-A^2 - \frac{1}{A^2}$
4.105	$A^{18} - A^{10} - A^6 - A^2$	$ \begin{array}{c c} -A^2 - \frac{1}{A^2} \\ A^{18} - A^{10} - A^6 - A^2 \end{array} $
4.106	$-A^2 - \frac{1}{A^2}$	$-A^{10} + K_1^2 A^6 - A^6 - K_1^2 A^2$
4.107	$-A^2 - \frac{1}{4^2}$	$-A^2 - \frac{1}{A^2}$
4.108	$ \begin{array}{c} -A^2 - \frac{1}{A^2} \\ -A^2 - \frac{1}{A^2} \\ -A^{10} - \frac{1}{A^{10}} \end{array} $	$-A^{10} - \frac{1}{A^{10}}$

A.2 A Mathematica Program

A.2.1 A Parity Categorification

The following program for a categorification of the arrow polynomial and the forgetful parity version is based on Dror Bar-Natan's construction [4] for Khovanov homology. Here we implement a version of Gaussian elimination for computing homology with coefficients over \mathbb{Z}_2 that was pointed out to us by Marc Culler and implemented by Baldwin and Gillam for computation of Heegaard-Floer knot homology in [2]. This can be described graphically as in Figure 46 where we reduce based on the chosen marked edge. This is equivalent to applying Gaussian Elimination to the chain complex as in Figure 47 where we assume ϕ (the equivalent of the selected edge) is invertible. Maps denoted by \bullet are arbitrary and inconsequential in the final result. For more on Gaussian Elimination and homotopy equivalence we point the reader to [7].

Remark A.1. A similar program for Khovanov homology and the forgetful

parity version with \mathbb{Z}_2 coefficients is available on the first authors website.

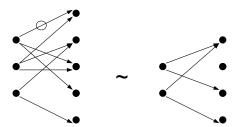


Figure 46:

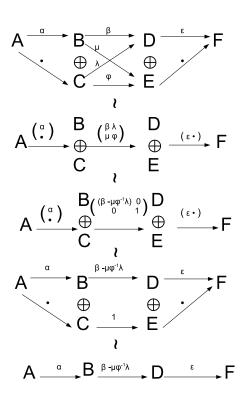


Figure 47:

```
np[L_PD] := Count[L, _X];
nm[L_PD] := Count[L, _Y];
SetAttributes[del, Orderless]
```

np and nm count the number of positive and negative crossings for a given planar diagram respectively. We set del to be orderless to reduce the number of necessary relations.

The following lines of program perform the forgetful mapping on the odd crossings.

```
EvenParityPD[L_PD] :=
Sort[L /. {X[i_, j_, k_, 1_] :>
         Odd[i, j, k, 1] /; OddQ[i - j]} /. {Y[i_, j_, k_, 1_] :>
         Odd[i, j, k, 1] /; OddQ[i - j]}]
```

EvenParity performs a simple check to determine if a given crossing is even or odd. For an odd crossing it replaces the head X or Y with Odd. Note this subroutine assumes that arcs of a given knot diagram are labeling consecutively.

OddIdentities creates a collection of arc relations displayed in terms of Kronecker deltas based on the odd crossings.

```
EvenCross[L_PD] :=
Drop[EvenParityPD[L],
  Length[EvenParityPD[L]] - (np[EvenParityPD[L]] +
    nm[EvenParityPD[L]])]
```

EvenCross collects the even crossings from a given PD code.

```
PDReduction[L_PD, d_del] := (mm := Min[d[[1]], d[[2]]];
    nn = Max[d[[1]], d[[2]]]; L /. {nn :> mm})
```

PDReduction turns a single identity produced by OddIdentities into a reduction relation and applies this relation.

```
ForgetfulEvenParityPD[L_PD] := (RedPD = EvenCross[L];
Do[RedPD = PDReduction[RedPD, OddIdentities[L][[i]]], {i,
    Length[OddIdentities[L]]}]; RedPD)
```

ForgetfulEvenParityPD applies PDReduction for all of the relations in OddIdentities and returns the resulting PD code.

```
rule2 = {del[a_, b_][m_] del[a_, b_][m_] :> del[a, a][m],
   del[a_, b_][m_] del[b_, c_][n_] :> del[a, c][Min[m, n]],
   del[a_, b_][m_] led[b_, c_][n_] :> led[a, c][Min[m, n]],
   del[a_, b_][m_] led[c_, b_][n_] :> led[c, a][Min[m, n]],
   led[a_, b_][m_] del[b_, c_][n_] :> led[a, c][Min[m, n]],
   led[a_, b_][m_] del[c_, b_][n_] :> led[a, c][Min[m, n]],
   led[a_, b_][m_] led[b_, c_][n_] :> del[a, c][Min[m, n]]};
rule3 = \{del[a_, a_][m1_] :> c[m1, 0, 0],
   del[a_, a_][m1_]^- :> c[m1, 0, 0],
   led[a_, b_][m1_]^2 :> c[m1, 1, 1],
   led[a_, b_][m1_] led[a_, b_][m2_] :> c[Min[m1, m2], 1, 1],
   led[a_, b_][m1_] led[x_, b_][m2_] led[x_, d_][m3_] led[a_, d_][
      m4_] :> c[Min[m1, m2, m3, m4], 2, 2],
   led[a_, b_][m1_] led[x_, b_][m2_] led[x_, d_][m3_] led[e_, d_][
      m4_] led[e_, f_][m5_] led[a_, f_][m6_] :>
    c[Min[m1, m2, m3, m4, m5, m6], 3, 1],
   led[a_, b_][m1_] led[x_, b_][m2_] led[x_, d_][m3_] led[e_, d_][
      m4_] led[e_, f_][m5_] led[g_, f_][m6_] led[g_, h_][
      m7_] led[a_, h_][m8_] :>
    c[Min[m1, m2, m3, m4, m5, m6, m7, m8], 4, 3],
   led[a_, b_][m1_] led[x_, b_][m2_] led[x_, d_][m3_] led[e_, d_][
     m4_] led[e_, f_][m5_] led[g_, f_][m6_] led[g_, h_][
      m7_] led[y_, h_][m8_] led[y_, z_][m9_] led[a_, z_][m10_] :>
    c[Min[m1, m2, m3, m4, m5, m6, m7, m8, m9, m10], 5, 1]};
```

rule2 and rule3 are reduction relations used by S. rule2 joins arcs and cusps while rule3 produces the labeled circles for a basic (unenhanced) state. We follow the convention c[m, p,k] is circle m with arrow number p and dot of order k. Where $p = 1*2^(k - 1)$ for 1 odd.

 ${\tt ruleStar}$ is a reduction relations used by S which produces notation corresponding to a bifurcation on an edge denoted by * on the cube complex.

```
S[L_PD, a_List] :=
```

S produces the unenhanced state of the cube complex for L corresponding to the vertex a.

```
MG[expr] :=
expr //. {c[m_, 0, k_] :> 1} //. {c[m_, p_, k_] :>
a[p]} //. {a[i_]^_ :> a[i]}
```

MG computes the multiple grading for an given unenhanced state. If there is no arrow numbers MG returns 1. If there are arrow numbers MG returns a product of the form $a[i_1]a[i_2]\ldots a[i_n]$, where the i_j are the distinct arrow numbers (ie $i_j=i_k$ iff j=k).

```
Deg[expr_] := Count[expr, _v1, {0, 1}] - Count[expr, _vX, {0, 1}]
V[L_PD, s_String, deg___] :=
    V[L, Characters[s] /. {"0" -> 0, "1" -> 1}, deg]
V[L_PD, a_List] :=
    List @@ Expand[S[L, a] /. x_c :> ((vX @@ x) + (v1 @@ x))]
V[L_PD, a_List, deg_Integer] :=
    Select[V[L, a], (deg == Deg[#] + (Plus @@ a)) &]
```

The above subroutines provide information on the enhanced states. V = c[m,p,k] by vX[m,p,k]+v1[m,p,k] throughout then expands each expression. Each summand corresponds to an enhanced (labeled by X and 1) state, which we separate into a list of enhanced states at each vertex. Deg computes (# X's - #1's)) and when given to V returns enhanced states with a given bi-degree. ((bi-degree) = (homological degree) + (# X's - #1's))

We need to compute the vector grading of an enhanced state. Recall that this (inf. dim.) vector is the sum over the labeling in the enhanced state where, for i>0, we transform $\mathtt{vX[*,*,i]}$ into the vector that is 1 in the i^th position and 0 elsewhere and similarly we transform $\mathtt{v1[*,*,i]}$ into the vector that is -1 in the i^th position and 0 elsewhere. VG returns 1 if the vector grading is the zero vector else it returns the product of terms of the form $\mathtt{v[k, n]}$ corresponding to the k^th position in the vector grading having value n.

```
d[L_PD, s_String] := d[L, Characters[s] /. {"0" -> 0, "1" -> 1}]
d[L_PD, a_List] :=
S[L, a] //. \{(c[x_{-}] c[y_{-}] \rightarrow c[z_{-}])*. :> \{v10x v10y \rightarrow 0,
         v10x vX0y -> 0, vX0x v10y -> 0,
         vX@x vX@y \rightarrow 0 /; (MG[S[L, a //. {"*" \rightarrow 0}]] = !=
         MG[S[L, a //. {"*" -> 1}]]), (c[z_] ->
         c[x_{-}] c[y_{-}])*_{-} :> \{v1@z -> 0,
        vX@z \rightarrow 0 /; (MG[S[L, a //. {"*" \rightarrow 0}]] =!=
         MG[S[L, a //. {"*" -> 1}]]) } //. {(c[x_] c[y_] -> 1)} } //. }
         c[z_{-}])*_. :> {v10x v10y -> v10z, v10x vX0y -> vX0z,
       vX@x v1@y -> vX@z,
       vX@x vX@y ->
         O} /; (VG[v10x v10y] === VG[v10z]) && (VG[v10x vX0y] ===
         VG[vX@z]) \&\& (VG[vX@x v1@y] === VG[vX@z]), (c[x__] c[y__] ->
        c[z_{-}])*_. :> {v10x v10y -> 0, v10x vX0y -> vX0z,
       vX@x v1@y -> vX@z,
       vX@x vX@y ->
        0} /; (VG[v10x v10y] =!= VG[v10z]) && (VG[v10x vX0y] ===
         VG[vX@z]) && (VG[vX@x v1@y] === VG[vX@z]), (c[x_] c[y_] ->
        c[z_{-}])*_{-}: > \{v10x \ v10y \rightarrow v10z, \ v10x \ vX0y \rightarrow 0,
       vX@x v1@y \rightarrow vX@z,
       vX@x vX@y ->
        0} /; (VG[v1@x v1@y] === VG[v1@z]) && (VG[v1@x vX@y] =!=
         VG[vX@z]) \&\& (VG[vX@x v1@y] === VG[vX@z]), (c[x_] c[y_] ->
        c[z_{-}])*_. :> {v10x v10y -> v10z, v10x vX0y -> vX0z,
       vX@x v1@y -> 0,
       vX@x vX@y ->
        0} /; (VG[v10x v10y] === VG[v10z]) && (VG[v10x vX0y] ===
         VG[vX@z]) && (VG[vX@x v1@y] = != VG[vX@z]), (c[x_{-}] c[y_{-}] \rightarrow
        c[z_{-}])*_. :> {v1@x v1@y -> 0, v1@x vX@y -> 0,
       vX@x v1@y \rightarrow vX@z,
       vX@x vX@y ->
         O} /; (VG[v1@x v1@y] =!= VG[v1@z]) && (VG[v1@x vX@y] =!=
         VG[vX@z]) \&\& (VG[vX@x v1@y] === VG[vX@z]), (c[x_] c[y_] ->
        c[z_{-}])*_. :> {v1@x v1@y -> 0, v1@x vX@y -> vX@z,
       vX@x v1@y -> 0,
       vX@x vX@y ->
         O} /; (VG[v10x v10y] =!= VG[v10z]) && (VG[v10x vX0y] ===
         VG[vX@z]) && (VG[vX@x v1@y] = != VG[vX@z]), (c[x_{-}] c[y_{-}] \rightarrow
        c[z_{-}])*_. :> {v1@x v1@y -> v1@z, v1@x vX@y -> 0,
       vX0x v10y -> 0,
```

```
vX@x vX@y ->
 0} /; (VG[v1@x v1@y] === VG[v1@z]) && (VG[v1@x vX@y] =!=
  \label{eq:vx0z} VG[vX0z]) && (VG[vX0x v10y] = != VG[vX0z]), (c[x_{-}] c[y_{-}] ->
 c[z_{-}])*_. :> {v1@x v1@y -> 0, v1@x vX@y -> 0, vX@x v1@y -> 0,
 vX@x vX@y ->
 O} /; (VG[v1@x v1@y] =!= VG[v1@z]) && (VG[v1@x vX@y] =!=
  VG[vX@z]) && (VG[vX@x v1@y] = != VG[vX@z]), (c[z_{-}] \rightarrow vG[vX@z])
 c[x_{-}] c[y_{-}] *_{-} :> \{v10z -> v10x vX0y + vX0x v10y,
vX@z ->
 vX@x vX@y} /; (VG[v1@z] === VG[v1@x vX@y]) && (VG[v1@z] ===
  VG[vX@x v1@y]) \&\& (VG[vX@z] === VG[vX@x vX@y]), (c[z__] ->
 c[x_{-}] c[y_{-}])*_{-} :> \{v1@z -> vX@x v1@y,
vX@z ->
 vX0x vX0y} /; (VG[v10z] =!= VG[v10x vX0y]) && (VG[v10z] ===
  VG[vX@x v1@y]) \&\& (VG[vX@z] === VG[vX@x vX@y]), (c[z_] ->
 c[x_{-}] c[y_{-}])*_{-} :> \{v1@z -> v1@x vX@y,
vX@z ->
 vX@x vX@y} /; (VG[v1@z] === VG[v1@x vX@y]) && (VG[v1@z] =!=
  VG[vX@x v1@y]) \&\& (VG[vX@z] === VG[vX@x vX@y]), (c[z_] ->
 c[x_{-}] c[y_{-}] *_{.} :> {v10z -> v10x vX0y + vX0x v10y,}
 0} /; (VG[v1@z] === VG[v1@x vX@y]) && (VG[v1@z] ===
  VG[vX@x v1@y]) \&\& (VG[vX@z] = != VG[vX@x vX@y]), (c[z__] -> vX@y])
 c[x_{-}] c[y_{-}])*_{-} :> \{v1@z -> 0,
vX@z ->
 vX@x vX@y} /; (VG[v1@z] = != VG[v1@x vX@y]) && (VG[v1@z] = != VG[v1@x vX@y])
  VG[vX@x v1@y]) \&\& (VG[vX@z] === VG[vX@x vX@y]), (c[z_] ->
 c[x_{-}] c[y_{-}])*_{-} :> \{v1@z -> vX@x v1@y,
vX@z ->
 0} /; (VG[v10z] =!= VG[v10x vX0y]) && (VG[v10z] ===
  VG[vX@x v1@y]) \&\& (VG[vX@z] = != VG[vX@x vX@y]), (c[z__] -> vX@y])
 c[x_{-}] c[y_{-}])*_{-} :> \{v1@z -> v1@x vX@y,
vX@z ->
 0} /; (VG[v1@z] === VG[v1@x vX@y]) && (VG[v1@z] =!=
  VG[vX@x v1@y]) \&\& (VG[vX@z] =!= VG[vX@x vX@y]), (c[z_] ->
 c[x_{-}] c[y_{-}])*_{-} :> \{v1@z -> 0,
vX@z ->
 0} /; (VG[v1@z] =!= VG[v1@x vX@y]) && (VG[v1@z] =!=
 VG[vX@x v1@y]) \&\& (VG[vX@z] = != VG[vX@x vX@y]) } //. {(c[
 x_{-}] -> c[y_{-}])*_. :> {v1@x -> 0, vX@x -> 0}}
```

d computes the edge morphism for the edge corresponding to the label a. Here a is a list of 0's and 1's along with a single * where * corresponds to the crossing we are resmoothing and 0 and 1 correspond to A- and A^{-1} -smoothings at the remaining crossings.

We now have enough to construct the cube complex. The following collection of routines together collect this information and constructs a graph. We then preform the previously mentioned graphical reduction algorithm to compute the homology.

```
dif[L_PD, s_String] := dif[L, Characters[s] /. {"0" -> 0, "1" -> 1}]
```

dif constructs the set of directed edges for the graph corresponding to an edge of the cube complex. It does the locally by applying the differential d to the tail of each edge. Comp produces the full set of vertices for the graph and connected the heads and tails of the directed edges formed by dif. Some zero differentials remain. Edges removes these from the list.

```
KhColumn[L_PD, r_Integer] :=
   If[r < 0 || r > (np[L] + nm[L]), {0},
      Join @@ (((v @@ #) V[L, #]) & /@
      Permutations[
          Join[Table[0, {(np[L] + nm[L]) - r}], Table[1, {r}]]])];
Gens[L_PD] :=
   Cases[Flatten[{KhColumn[L, #] & /@ Range[0, (np[L] + nm[L])]}],
      Except[0]];
```

Gens produces the collection of enhanced states corresponding to the enhanced states of the complex (i.e. the nodes in the graph) by calling KhColumn for each homological degree of the planar diagram for the knot.

```
Perms[L_PD] :=
   Join @@ (Permutations[
        Join[{"*"}, Table[0, {(np[L] + nm[L]) - # - 1}],
        Table[1, {#}]]] & /@ Range[0, (np[L] + nm[L]) - 1]);
```

Perms generates the lists of 0's, 1's and a single * corresponding to the edges of the cube complex.

```
Height[gen__] := (gen /. {v1[a__] :> 1, vX[b__] :> 1,
    v[c__] :> Plus[c]});
EdgeHeight[e_] := If[IntegerQ[e], -1, Height[e[[1]]]];
MultGrad[e_] :=
  e /. {v[expr__] :> 1, vX[a_, b_, c_] :> K[b],
    v1[a_, b_, c_] :> K[b]} /. {K[0] :> 1} /. {K[i_]^_ :> K[i]};
```

MultGrad takes a homology class representative and outputs its multiple grading.

```
AddDelEdges[edges_List, e_edge] := (Off[Part::partd];
  listfs = Select[edges, #[[2]] == e[[2]] &];
  listgs = Select[edges, #[[1]] == e[[1]] &];
  remfs = Rule[#, 0] & /@ listfs; remgs = Rule[#, 0] & /@ listgs;
  sym = edges /. remfs /. remgs /. {edge[e[[2]], ___] :> 0};
  diff = Tuples[{listfs,listgs}] /.
    {{edge[f1__, e2__], edge[e1__, g2__]} :> edge[f1, g2]};
  symdiff =
   If[(listfs == {}) || (listgs == {}), sym,
    Union[Complement[diff, sym], Complement[sym, diff]]];
  On[Part::partd]; symdiff)
```

Given an edge e, AddDelEdges looks for all local subgraphs which share the same head as e. It then computes a symmetric difference with collection of edges whose tail is the same as e.

```
Reduc[gens_List, edges_List,
   e_edge] := (Checks[(gens /. {e[[1]] :> 0, e[[2]] :> 0}),
   AddDelEdges[edges, e]]);
Checks[gens_List, unsortededges_List] := (
   edges = Cases[(SortBy[unsortededges, EdgeHeight[#] &]), Except[0]];
   If[edges == {}, Cases[gens, Except[0]],
    Reduc[gens, Delete[edges, 1], edges[[1]]]]);
```

Checks looks for the remaining edge whose head is in the highest homological degree. It then applies Reduc to remove the edge and apply the symmetric difference algorithm in AddDelEdges.

```
HomReps[L_PD] :=
Block[{$IterationLimit = Infinity, $RecursionLimit = Infinity},
Checks[Cases[Gens[L], Except[0]], Cases[Edges[L], Except[0]]];
```

HomReps takes a planar diagram code, repeatedly applies Checks to run the graph reduction algorithm and outputs representatives for the homology classes.

```
QT[gen___, L_PD] :=
   (r = (Height[gen] - nm[L]); (t^r)
     *(q^(r + Deg[gen] + np[L] - nm[L])));
```

QT computes the associated powers of q and t for a given representative of a homology class.

```
AKh[L_PD] :=
   Plus @@ (QT[#, L]*VG[# /. {v[a___] :> 1}]*
        MultGrad[# /. {v[a___] :> 1}] & /@ HomReps[L]);
ParityAKh[L_PD] :=
   If[Length[ForgetfulEvenParityPD[L]] == 1 ||
        Head[ForgetfulEvenParityPD[L]] === PDReduction, q + q^(-1),
```

```
Plus @@ (QT[#, ForgetfulEvenParityPD[L]]*VG[# /. {v[a__] :> 1}]*
    MultGrad[# /. {v[a__] :> 1}] & /@
    HomReps[ForgetfulEvenParityPD[L]])];
```

Finally, AKh and ParityAKh compute the corresponding categorifications for a given planar diagram L.

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